

Impact of Sleep Time on Truck Driver Performance Over Long Driving Shift

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Background

- Truck crashes: major safety hazard for commercial truck drivers.
- Fatigue: major risk factor for long-haul truck drivers.
- Sleep: important factor affecting fatigue.
 - Drivers who slept less prior to trips would be more likely to involve in safety-critical events.
 - Breaks (including sleep) before driving are beneficial in reducing safety-critical events.
- Motivation
 - To evaluate the temporal profile of driving performance in a long shift.
 - To compare driving performance among drivers with

sleep prior to a shift $\left\{ \begin{array}{l} < 7 \text{ hours,} \\ 7\text{--}9 \text{ hours,} \\ > 9 \text{ hours.} \end{array} \right.$

Data Collection

- Participants
 - 100 drivers from 4 for-hire trucking companies.
 - Followed up for around 4 weeks.
- Driving Data
 - Naturalistic data collection approach.
 - Truck fitted with unobtrusive data-collection equipment.
 - Data recorded from ignition-on to ignition-off at high frequency.



Figure: Photo: Five video camera images [2].

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- Activity Data
 - Drivers self-reported using a daily activity registry.

DATE: _____ DRIVER: _____

Mid Week 1 2 3 4 5 6 7 8 9 10 11 12 Noon 1 2 3 4 5 6 7 8 9 10 11 12

Activity Codes		Medications/Caffeine Use:		
		Time	Type	Amount/Dosage
Tasks During Driving Duty:				
1	Driving Truck			
2	Heavy Work (loading/unloading)			
3	Sleep			
4	Rest (not asleep)			
5	Eating			
6	Light Work (mailing, paperwork, vehicle maint.)			
Off-Duty Tasks:				
7	Sleep			
8	Rest (not asleep, watching TV, reading)			
9	Eating			
10	Light House Work (dishes)			
11	Heavy House Work (mowing lawn)			
12	Light Leisure Activity (reading, internet)			
13	Heavy Leisure Activity (golfing, sports)			
14	Driving Other Vehicle (not work-related)			
15	Other			

Figure: A sample of the daily activity register [2].

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- Activity Data
 - Drivers self-reported using a daily activity registry.
- Safety-Critical Events
 - Crash;
 - Near-crash;
 - Crash relevant conflict;
 - Unintentional lane deviation.

Data Processing

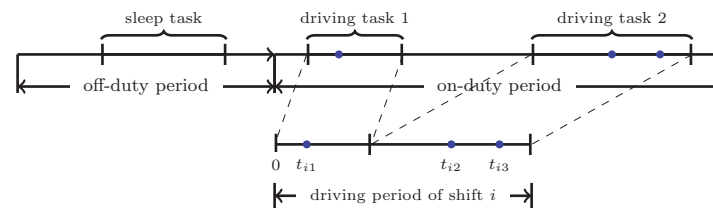


Figure: Illustration of data processing. Dots represent events, and t_{ij} , where $j = 1, 2, 3$, represents the driving time to event j in shift i .

1,880 shifts from 96 drivers contain valid sleep data.

- Off-duty sleep < 7 hours: 388 (20.6%) shifts;
- Off-duty sleep in 7–9 hours: 1,095 (58.2%) shifts;
- Off-duty sleep > 9 hours: 397 (21.1%) shifts.

Sleep Hours vs Driving Length

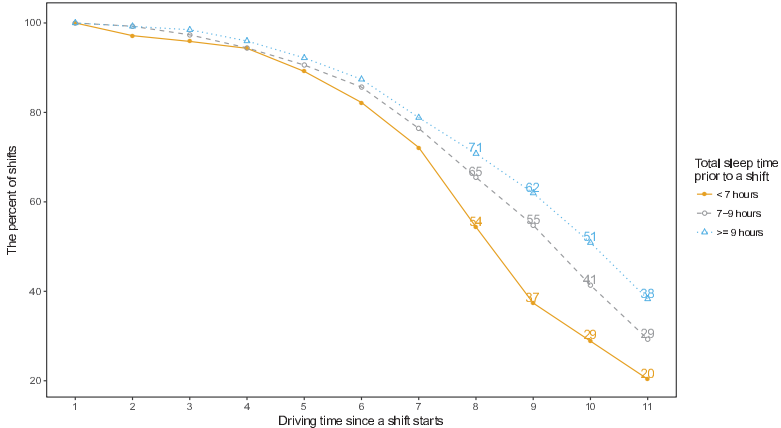


Figure: The percent of shifts driving into the 1st-11th driving hour by sleep time group.

Sleep Hours vs Breaks

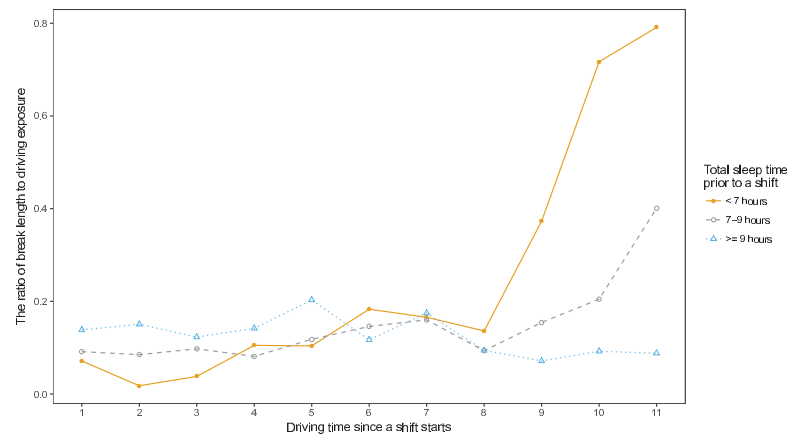
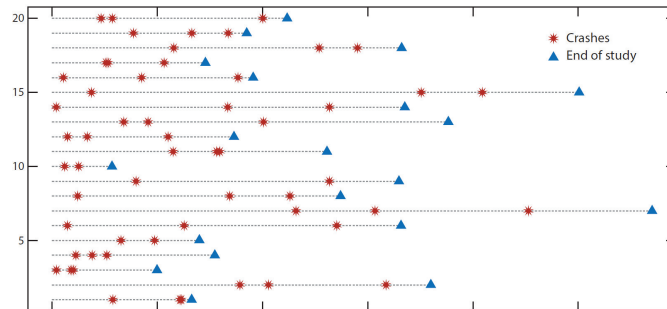


Figure: The ratio of break length (in hours) to driving exposure (in hours) in the 1st–11th driving hours by sleep time group. Exposure in the i th hour, where $i = 1, \dots, 11$, is the total driving time for all shifts that occurred in the i th hour.

Overview

2 Time-Varying Coefficient Model for Recurrent Events



Notations

Consider a sample of I driving shifts. For $i = 1, \dots, I$,

- Counting process $\{N_i(t), t \geq 0\}$
 - $N_i(t)$: the number of events occurred over $[0, t]$.
 - $\Delta N_i(t)$: the number of events occurred over $[t, t + \Delta t)$.
- Covariates
 - $\mathbf{x}_i = (x_{i1}, \dots, x_{ip})'$ assumed to have constant coefficients.
 - $\mathbf{z}_i = (z_{i1}, \dots, z_{iq})'$ assumed to have time-varying coefficients.
- Process history at time t , $H_i(t) = \{N_i(s), 0 \leq s < t, \mathbf{x}_i, \mathbf{z}_i\}$.
- Gamma frailty $u_i \sim \text{Ga}(\text{shape} = 1/\phi, \text{rate} = 1/\phi)$
 - $E(u_i) = 1$;
 - $\text{var}(u_i) = \phi$.

Model

- Conditional on u_i , the intensity function is defined as

$$\lambda_i(t|H_i(t), u_i) = \lim_{\Delta t \downarrow 0} \frac{P(\Delta N_i(t) = 1 | H_i(t), u_i)}{\Delta t}.$$

- Assume $\{N_i(t), t \geq 0\} | \mathbf{x}_i, \mathbf{z}_i, u_i$ to be an independent Poisson process with conditional intensity function

$$\begin{aligned} \lambda_i(t | \mathbf{x}_i, \mathbf{z}_i, u_i) &= u_i \rho_i(t) \\ &= u_i \exp\{\mathbf{x}_i' \boldsymbol{\alpha} + \beta_0(t) + z_{i1} \beta_1(t) + \cdots + z_{iq} \beta_q(t)\}. \end{aligned}$$

- Let $\mu_i(t) = \int_0^t \rho_i(s) ds$. Marginal features of $\{N_i(t), t \geq 0\}$:
 - $E[N_i(t)] = \mu_i(t)$.
 - $\text{var}[N_i(t)] = \mu_i(t) + \phi \mu_i^2(t)$. \Leftarrow extra-Poisson variation
 - $\text{cov}[N_i(s_1, t_1), N_i(s_2, t_2)] = \phi \mu_i(s_1, t_1) \mu_i(s_2, t_2)$. \Leftarrow association between counts over disjoint intervals

Model: Time-Varying Coefficients

Penalized B-splines [3] for smooth estimation of $\beta_l(t)$, where $l = 0, 1, \dots, q$:

- Let $[t_{\min}, t_{\max}]$ be divided into k_l equal intervals by knots

$$t_{\min} = \zeta_{l0} < \zeta_{l1} < \dots < \zeta_{l, k_l} = t_{\max}.$$

- The B-splines basis of degree v

$$\mathbf{B}_l(t) = (B_{l1}(t), \dots, B_{l, K_l}(t))', \text{ where } K_l = k_l + v.$$

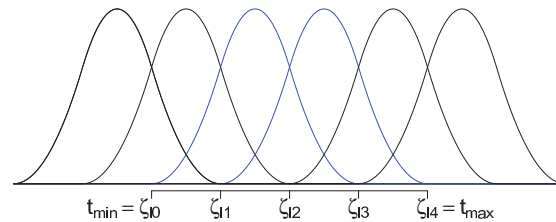


Figure: Illustration of the B-spline basis for $k_l = 4$ and $v = 2$.

Model: Mixed-Model Representation

Spline Parameters as Random Effects

Model

$$\lambda_i(t|\mathbf{x}_i, \mathbf{z}_i, u_i, \boldsymbol{\beta}_l) = u_i \exp \{ \mathbf{x}'_i \boldsymbol{\alpha} + \mathbf{B}'_0(t) \boldsymbol{\beta}_0 + \cdots + z_{iq} \mathbf{B}'_q(t) \boldsymbol{\beta}_q \},$$
$$u_i \sim \text{Ga}(1/\phi, 1/\phi), \quad \boldsymbol{\beta}_l \sim p(\boldsymbol{\beta}_l; \tau_l).$$

- Bayesian setting

$$\mathbf{D}_l \boldsymbol{\beta}_l = \begin{bmatrix} \Delta^r \beta_{l,r+1} \\ \vdots \\ \Delta^r \beta_{l,K_l} \end{bmatrix} \sim N \left(\mathbf{0}, \frac{1}{\tau_l} \mathbf{I} \right).$$

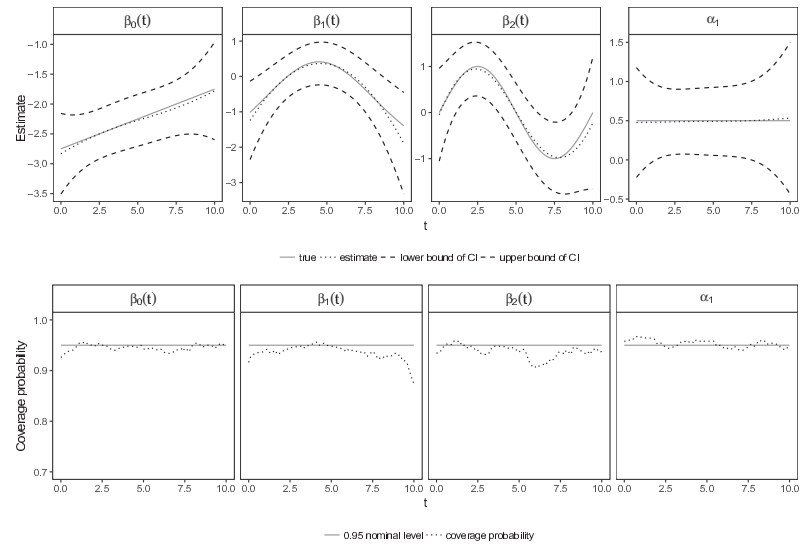
- Frequentist setting

$$p(\boldsymbol{\beta}_l; \tau_l) \propto \tau_l^{(K_l-r)/2} \exp \left\{ -\frac{1}{2} \tau_l \boldsymbol{\beta}'_l (\mathbf{D}'_l \mathbf{D}_l) \boldsymbol{\beta}_l \right\}.$$

- Inverse variance τ_l ($\Leftrightarrow \lambda_l$) controls the amount of smoothness.

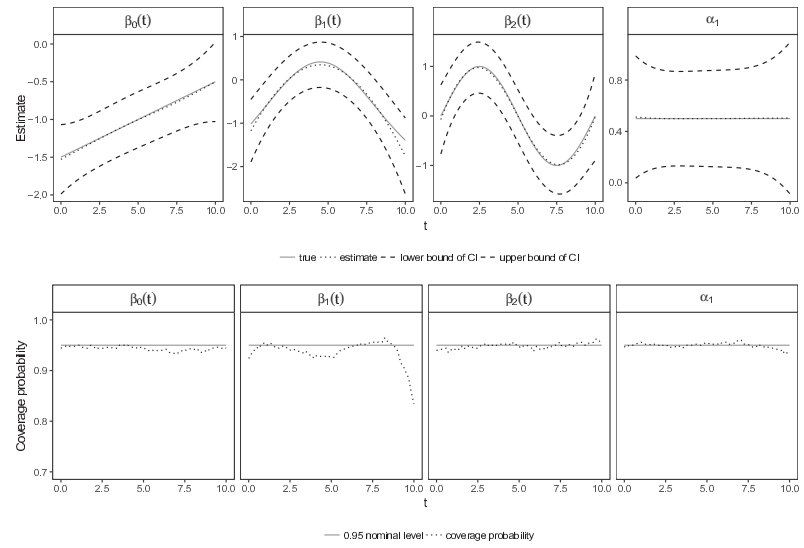
Simulation

Low Curvature TVC, Low Event Rate



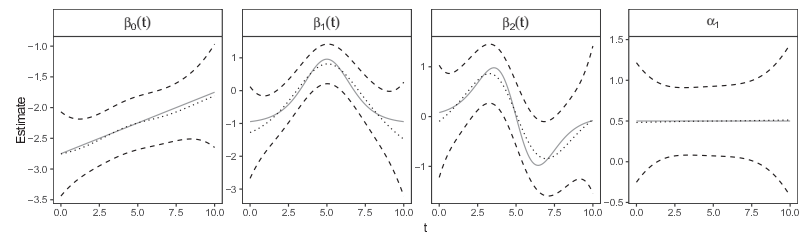
Simulation

Low Curvature TVC, High Event Rate

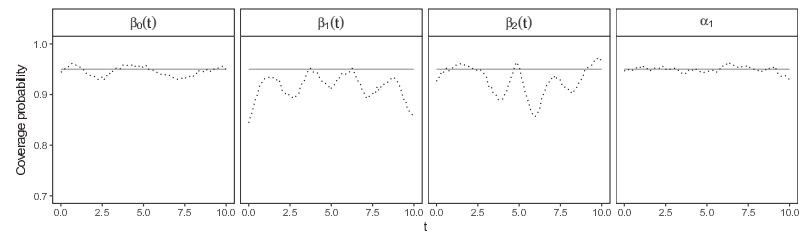


Simulation

High Curvature TVC, Low Event Rate



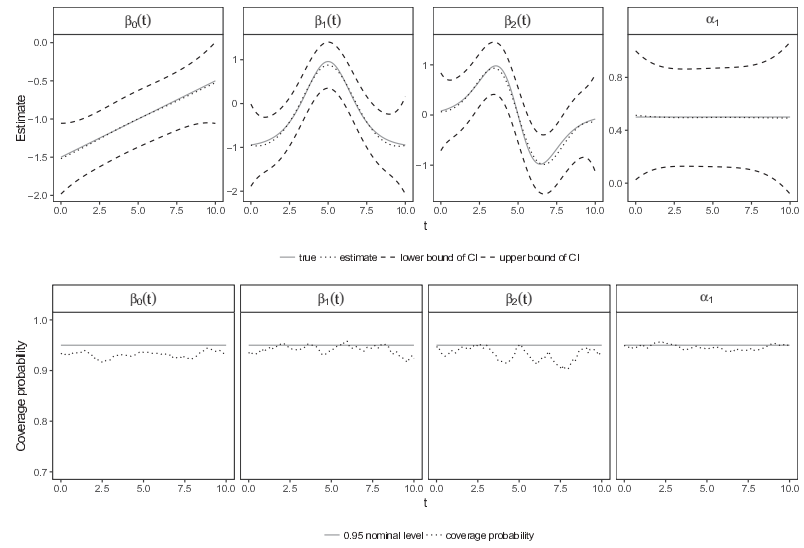
— true ··· estimate - - lower bound of CI - · - upper bound of CI



— 0.95 nominal level ··· coverage probability

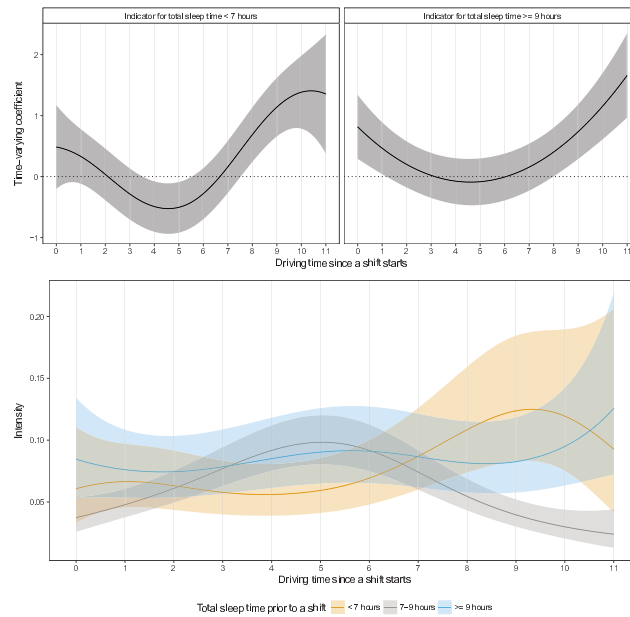
Simulation

High Curvature TVC, High Event Rate



Application

Within-Shifts: Unintentional Lane Deviation



Conclusions

- The total sleeping time is directly related to the total driving time
- The total sleeping time is directly related to breaks while driving
- The total sleeping time will affect driving performance after 8 hours of driving
- There is a complicated interaction effect among total sleeping time, breaks, and driving performance over long trips.

