



9th International Conference on
MANAGING PAVEMENT ASSETS (ICMPA9)

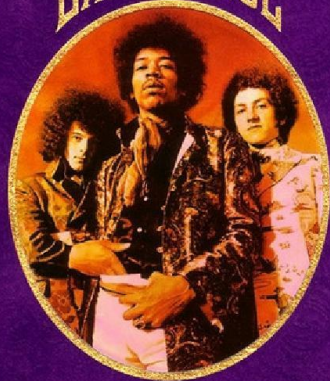
The Australian 3D Roughness Experience

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ARRB Group



Not to be confused with.....

THE
JIMI HENDRIX
EXPERIENCE



'all you do is slow me down, And I'm trying to get on the other side of town'

When you think of 3D, you probably think of....

- films
- 3D films were prominently featured in the 1950s in American cinema
- revival

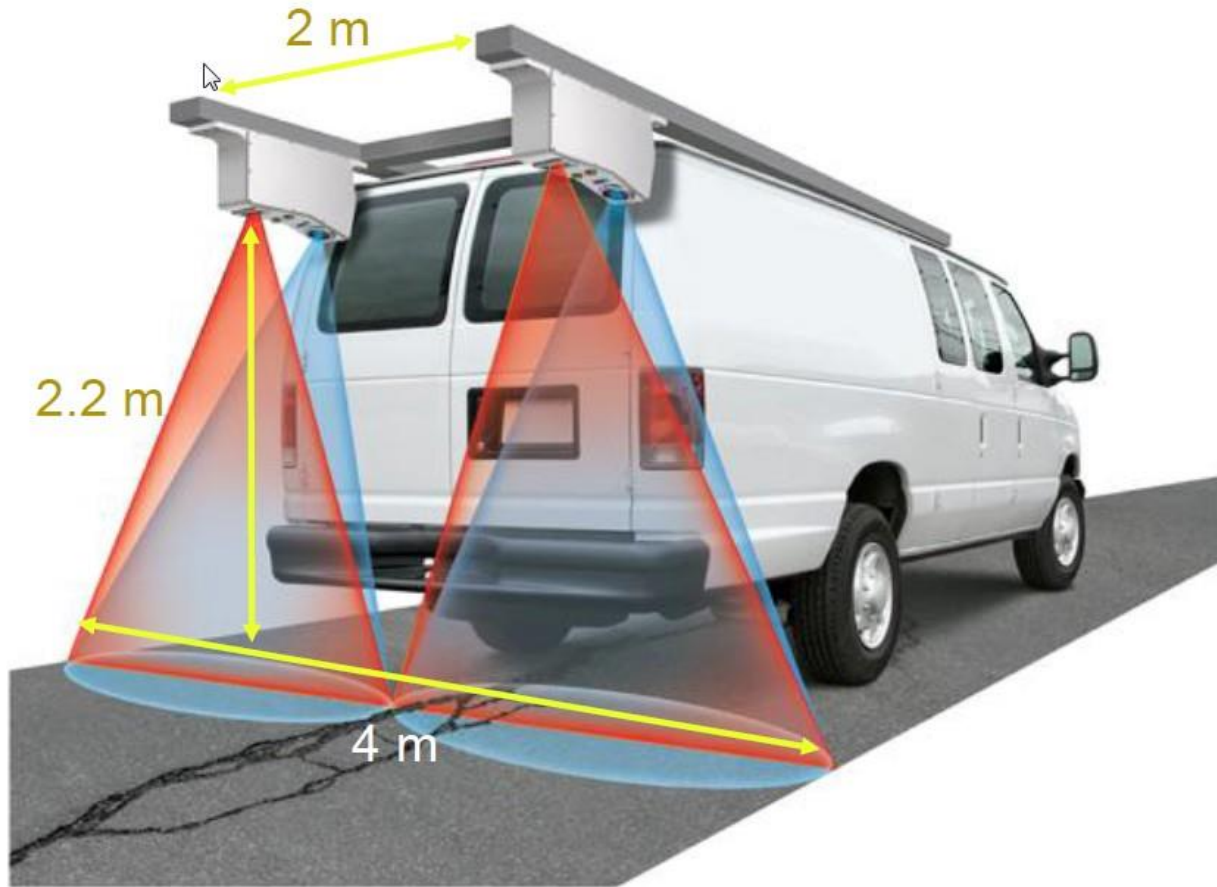
"Avatar-Teaser-Poster" by Source. Licensed under Fair use via Wikipedia - <http://en.wikipedia.org/wiki/File:Avatar-Teaser-Poster.jpg#/media/File:Avatar-Teaser-Poster.jpg>



Did you bring your glasses?

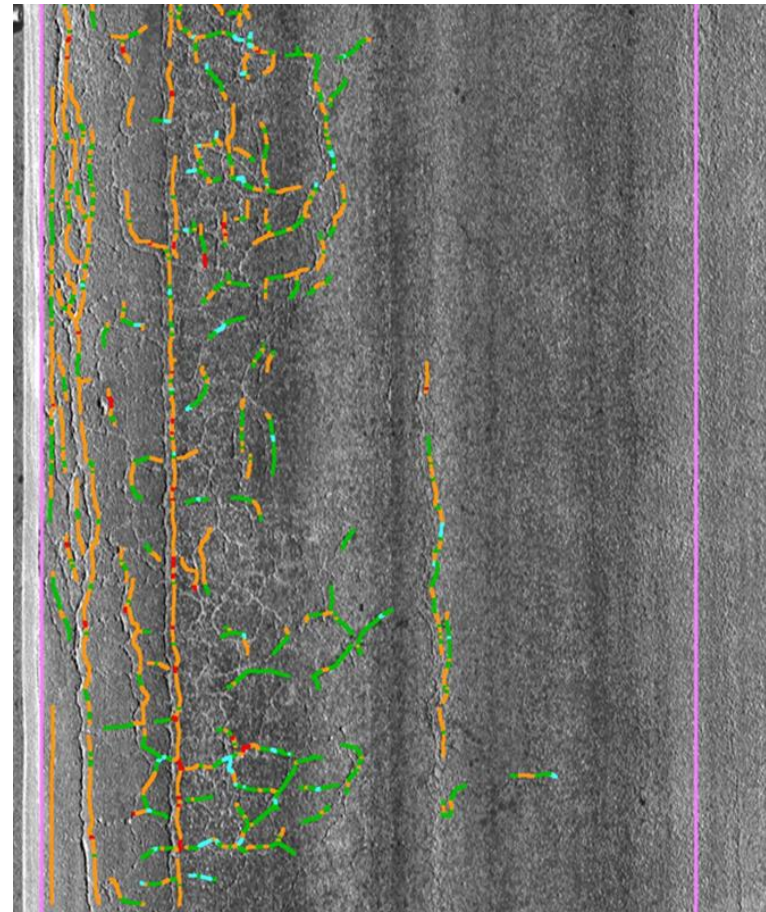
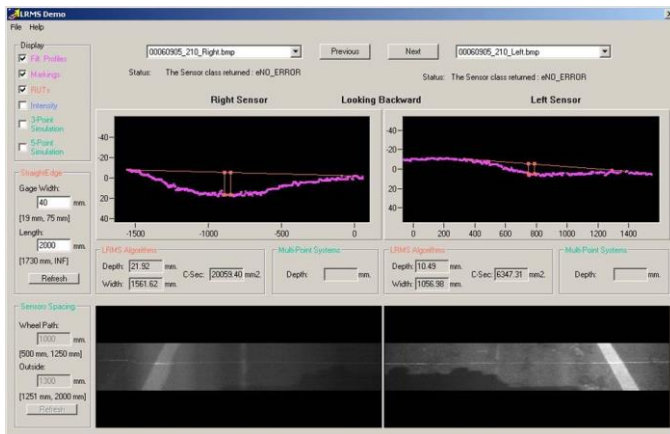
**THE AUSTRALIAN 3D
ROUGHNESS EXPERIENCE**

3D system



Typically used to measure....

- transverse profile
- cracking and other pavement defects

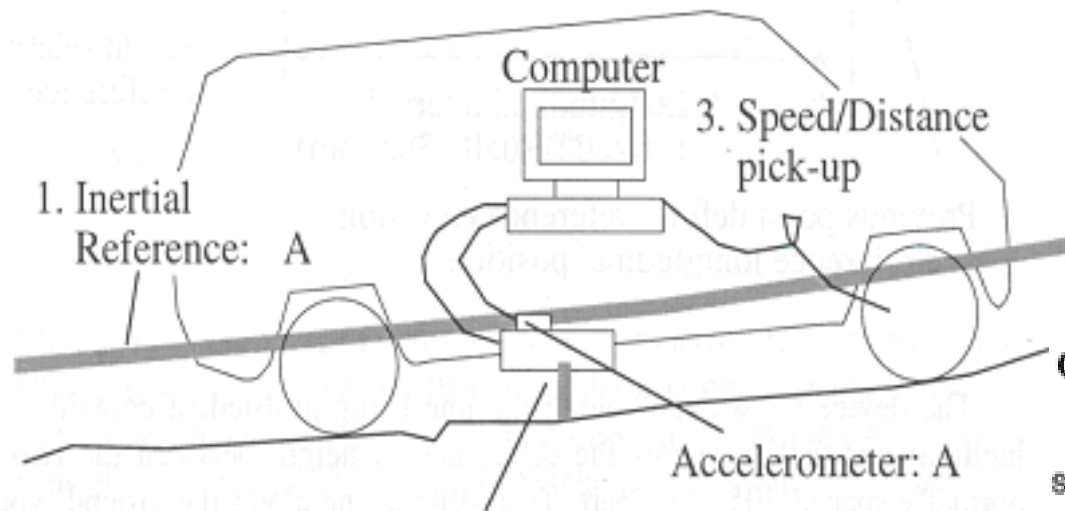


Wanted to determine.....

- Can 3D sensors be used to measure pavement roughness (smoothness)?
- Can the outputs meet current Australian standards?



Roughness - how measured?



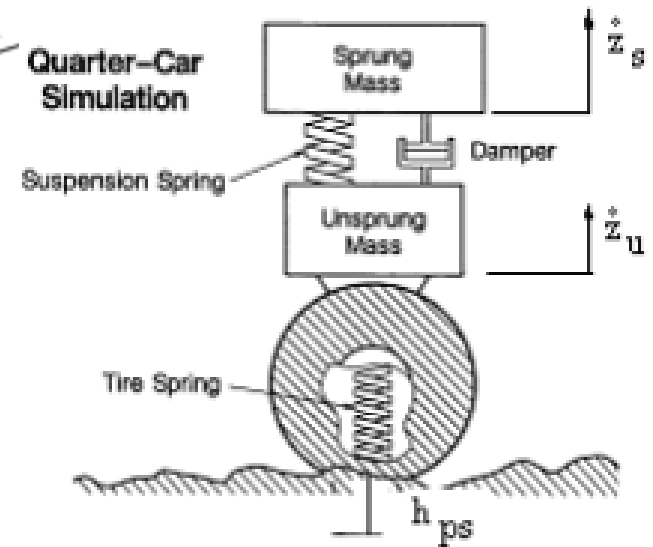
1. Inertial Reference: A

3. Speed/Distance pick-up

Accelerometer: A

2. Height relative to reference (laser, infrared, or ultrasonic sensor)

Little Book of Profiling, Sayers & Karamihas



The missing piece



Test methods

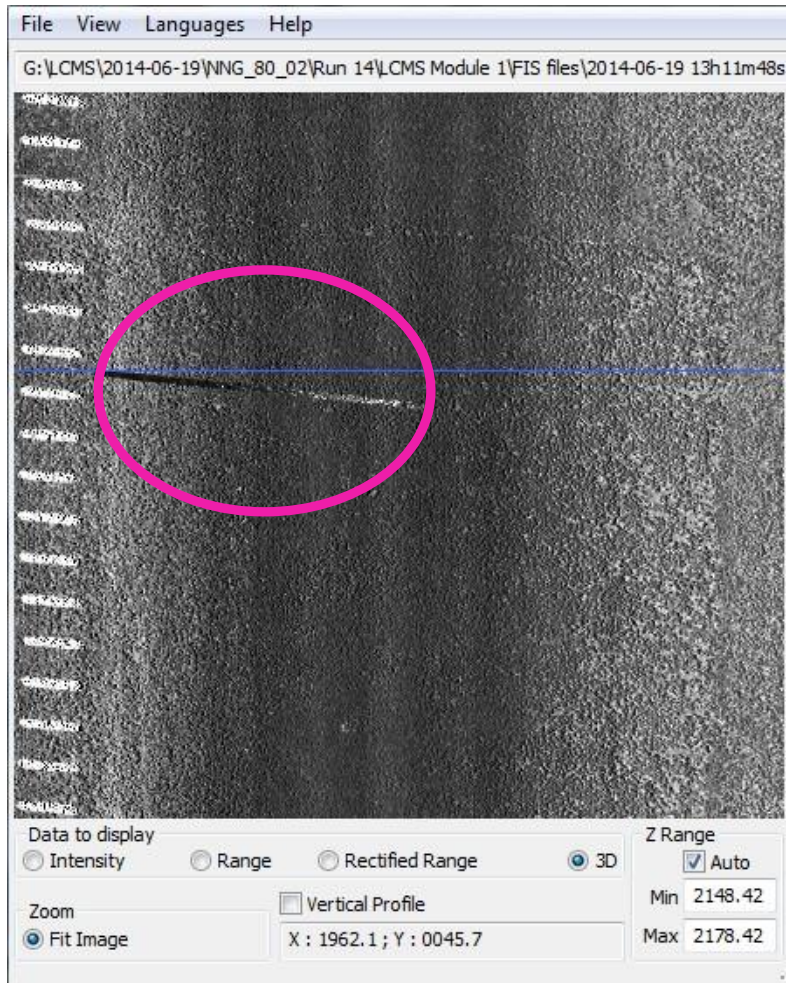
- **Cover a variety of pavement condition parameters**
- **Roughness**
 - **reference device**
 - **loop**



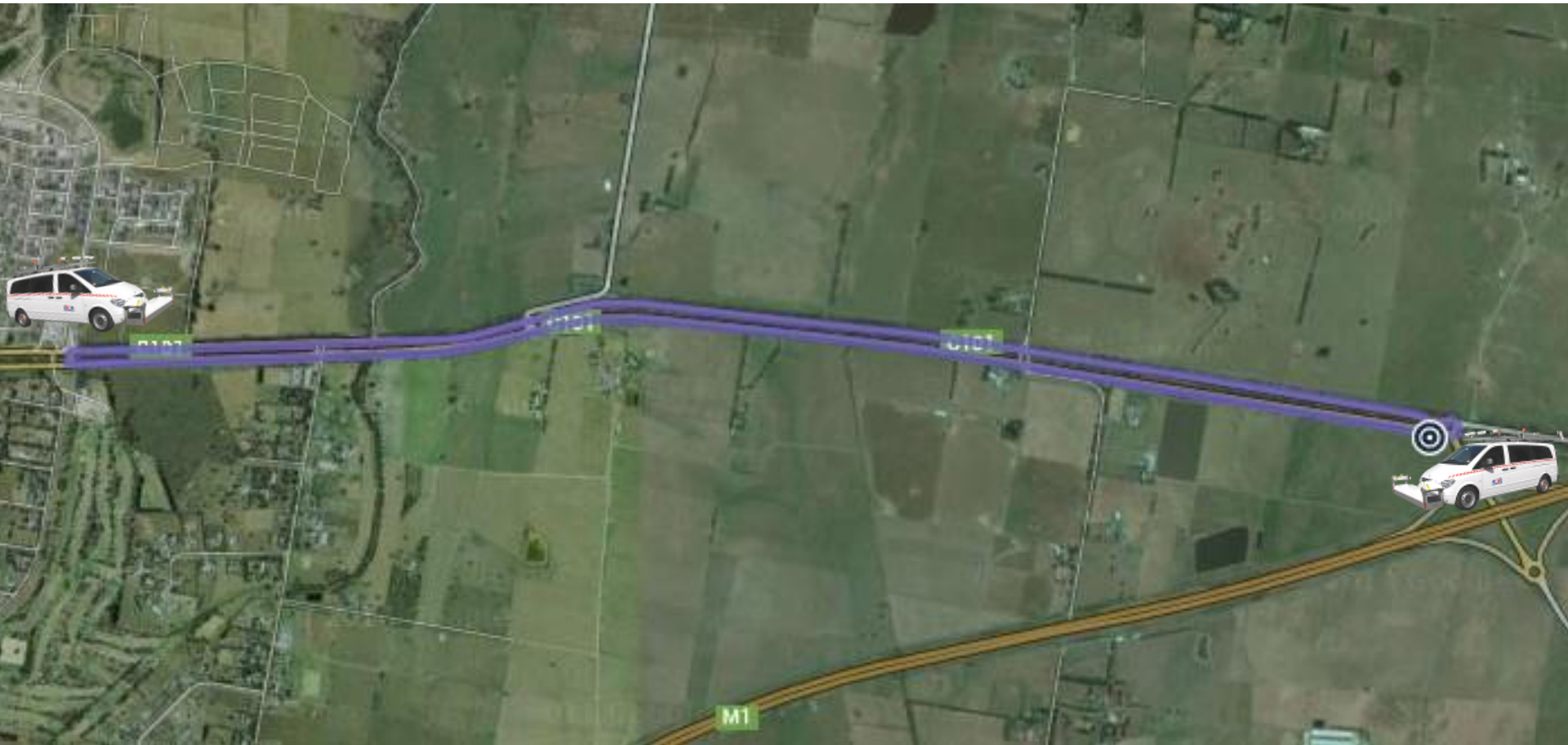
Experimental method



Experimental method



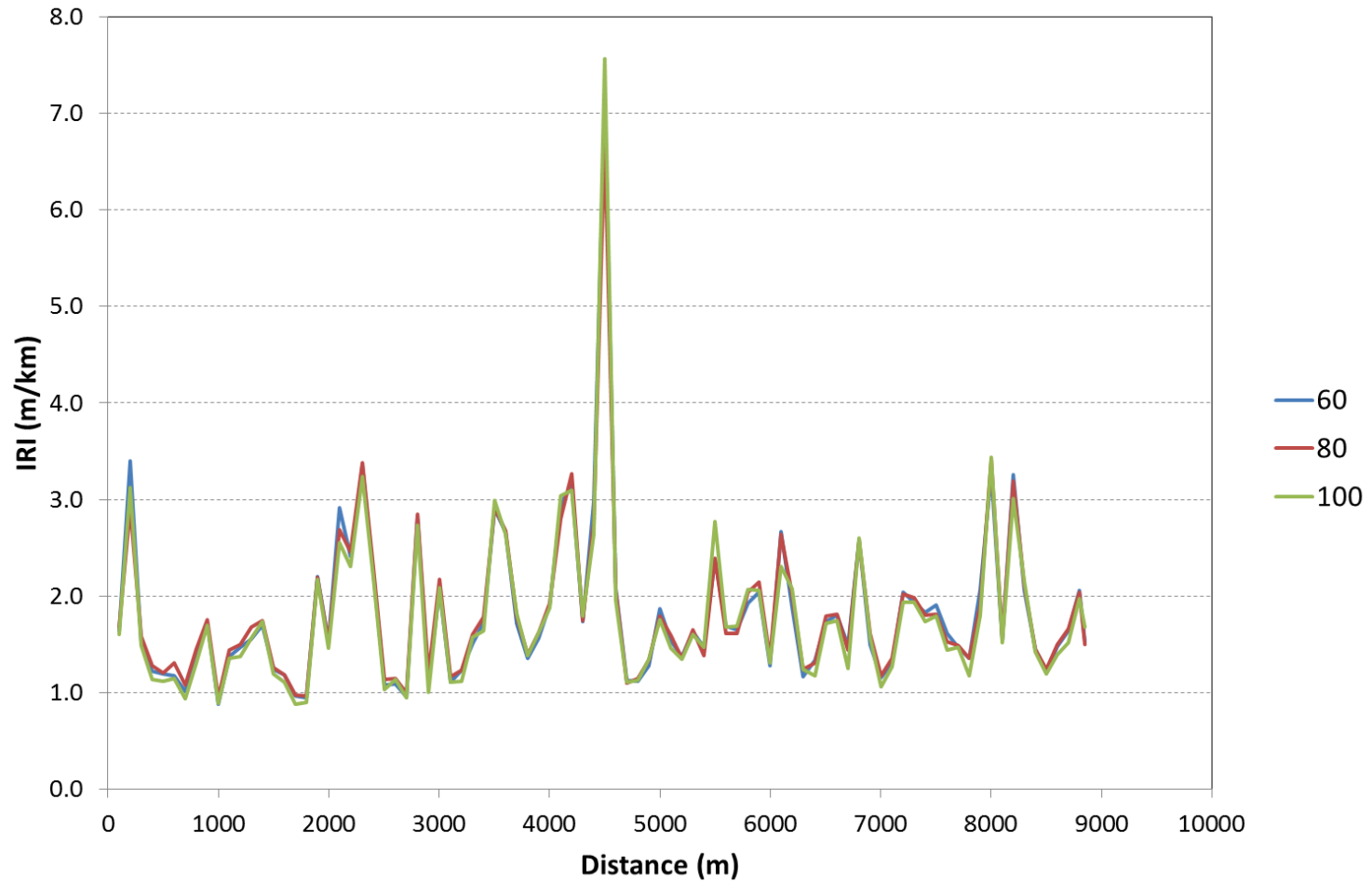
Loop method



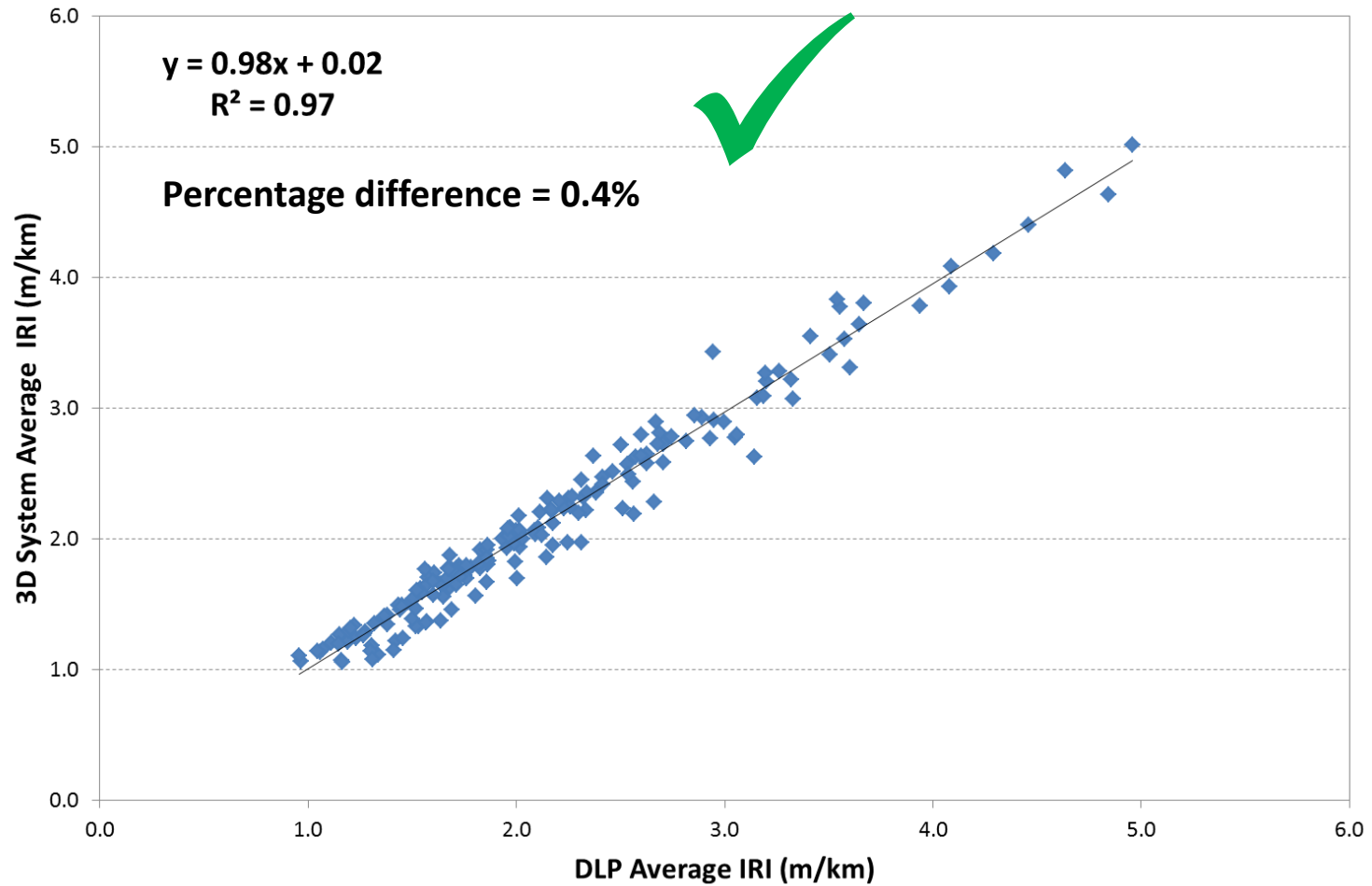
Loop method

- 5 repeat runs, loop length $\geq 10\text{km}$
- compare against reference data set
- pass/fail criteria
 - $R^2 \geq 0.95$
 - Ave percentage difference $\leq 5\%$

Results – loop method



Results – loop method



Reference device method



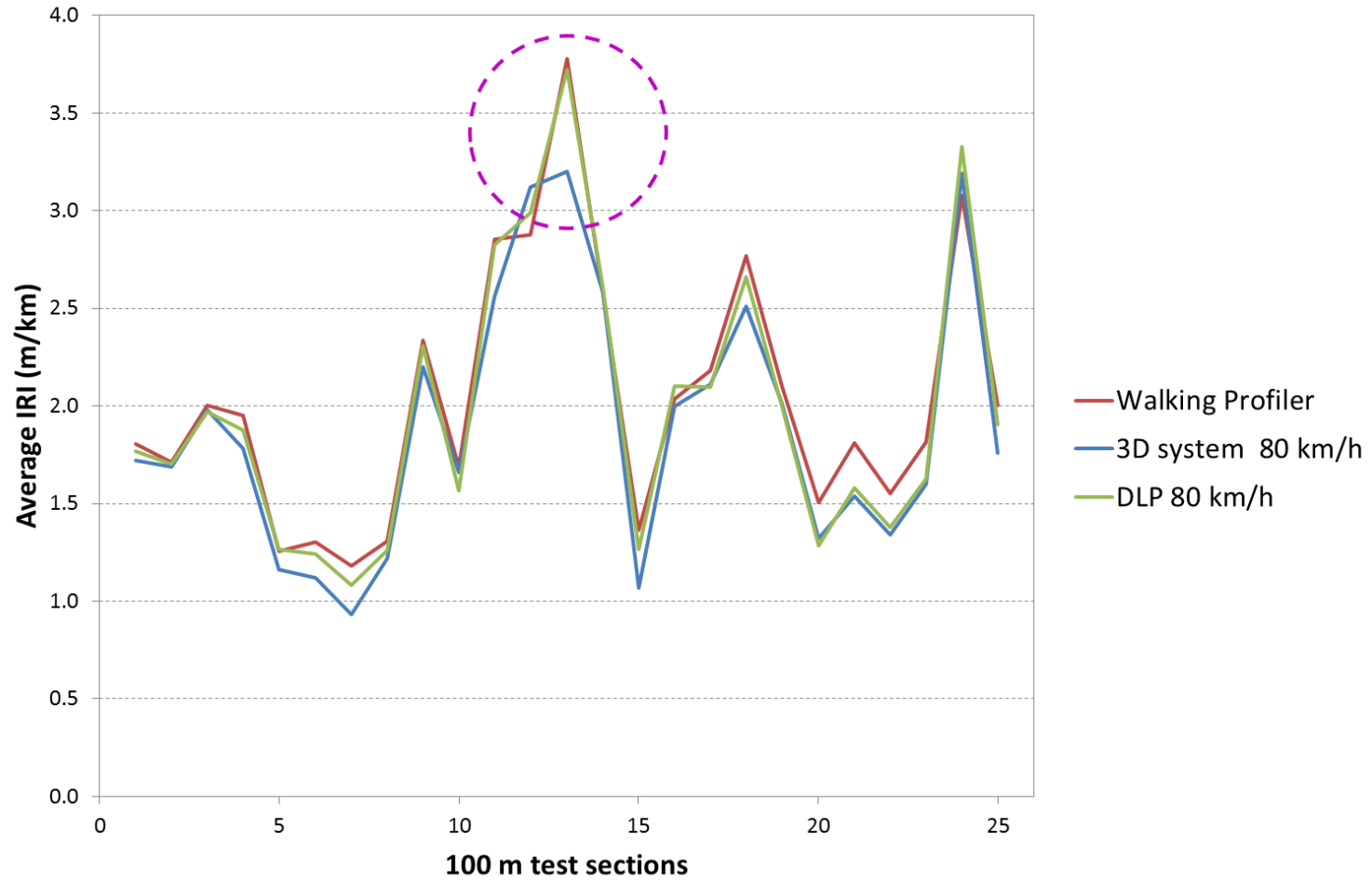
Reference device method

- five sites, 500m long, varying roughness
- three speeds plus combined
- pass/fail criteria
 - $R^2 \geq 0.95$
 - slope; $0.95 \leq A \leq 1.05$
 - Intercept; $-0.25 \leq B \leq 0.25$

Results – reference device method

Speed (km/h)	Parameter	Pass/Fail
60 (low)	Coefficient of determination (r^2)	Fail
	Slope	Pass
	Intercept (m/km)	Pass
80 (medium)	Coefficient of determination (r^2)	Fail
	Slope	Pass
	Intercept (m/km)	Pass
100 (high)	Coefficient of determination (r^2)	Fail
	Slope	Fail
	Intercept (m/km)	Pass
Combined	Coefficient of determination (r^2)	Fail
	Slope	Pass
	Intercept (m/km)	Pass

500m sites



Possible reasons for failure

- 15 months b/n collection of data sets
- differences in measurement line



Future work

- effect of curves
- frequency response
- third party validation
- undertake new reference device comparison
- assess texture measurement capability



Conclusion

- 3D sensors can be used to measure roughness
- meets the requirements of the loop test method but not the reference device
- possibly some minor speed dependency issues

Thank you

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3D ROUGHNESS
EXPERIENCE



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