

# Simulating effects of arousal on lane keeping: Are drowsiness and cognitive load opposite ends of a single spectrum?

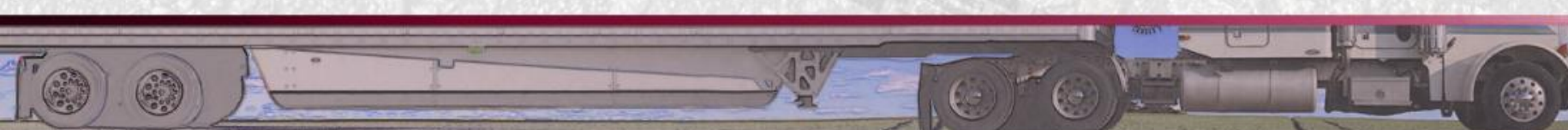
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# The opposite effects of drowsiness and cognitive load on lane keeping performance

## □ Definitions

- **Drowsiness:** Reduced level of *alertness*, where alertness is assumed to be governed by circadian cycle sleep homeostasis processes (Borbely and Achermann, 1999)
- **Cognitive load:** The demand for cognitive, or executive, control (imposed by non-visual, working-memory loading, secondary tasks such as phone conversation)

## □ Effects of drowsiness on lane keeping

- Increased lane keeping variability (Liu et al., 2009)
- Fewer small steering corrections but more large corrections (Thiffault and Bergeron, 2003)

## □ Effects of cognitive load on lane keeping

- *Reduced* lane-keeping variability (Atchley and Chan, 2011; Brookhuis et al. (1991), Beede and Kass, 2006; Becic et al., 2010; Cooper et al., 2013; Engström, Johansson and Östlund, 2005; He, 2012; He and McCarley, 2011; He, McCarley and Kramer, 2014; Horrey and Simons, 2007; Jamson and Merat, 2005; Knappe et al., 2007; Kubose et al., 2006; Liang and Lee, 2010; Mattes et al., 2007; Mazzae et al., 2005; Mehler et al., 2009; Medeiros-Ward et al., 2014; Merat and Jamson, 2008; Törnros and Bolling, 2005; Reimer, 2009; see He, 2012, and Engstrom et al., 2017, for a reviews).
- Increase in *small* steering corrections (Markkula and Engström, 2006; Engström (2011, paper III), Kountouriotis et al. (2016)



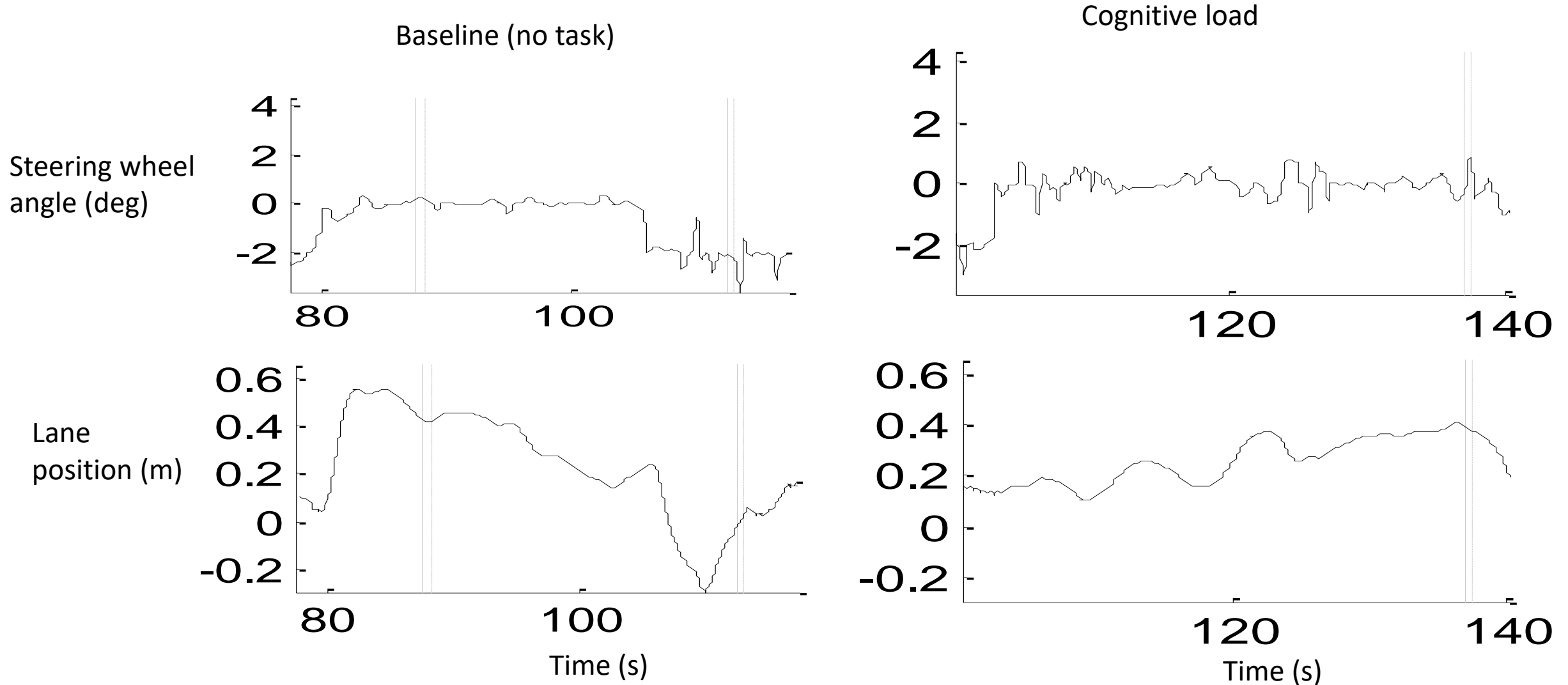
# Explanation for the effects of drowsiness on lane keeping (Liu et al., 2009)

- ❑ The drowsy driver cannot detect small lane deviations (which can be corrected by small steering wheel movements (SWMs))
- ❑ Large SWMs needed to correct for large lane deviations
- ❑ This leads to increased lane keeping variability, fewer small steering corrections but an increased frequency of large corrections



# Effects of cognitive load on lane keeping

Example data (Östlund et al., (2005))



# Proposed explanations for the lane keeping improvement effect of cognitive load

- ❑ The rigidified steering hypothesis (e.g., Reimer, 2009)
- ❑ The automatic steering hypothesis (Kubose et al., 2006; Medeiros-Ward et al., 2014)
- ❑ The visual enhancement hypothesis (Engström, 2011; Engström et al., 2005; Victor, 2006)
- ❑ The lateral prioritization hypothesis (Engström et al., 2005; He et al. (2014)
  
- ❑ However, all these hypotheses face challenges (see reviews in He et al., 2012, and Engstrom et al., 2017)



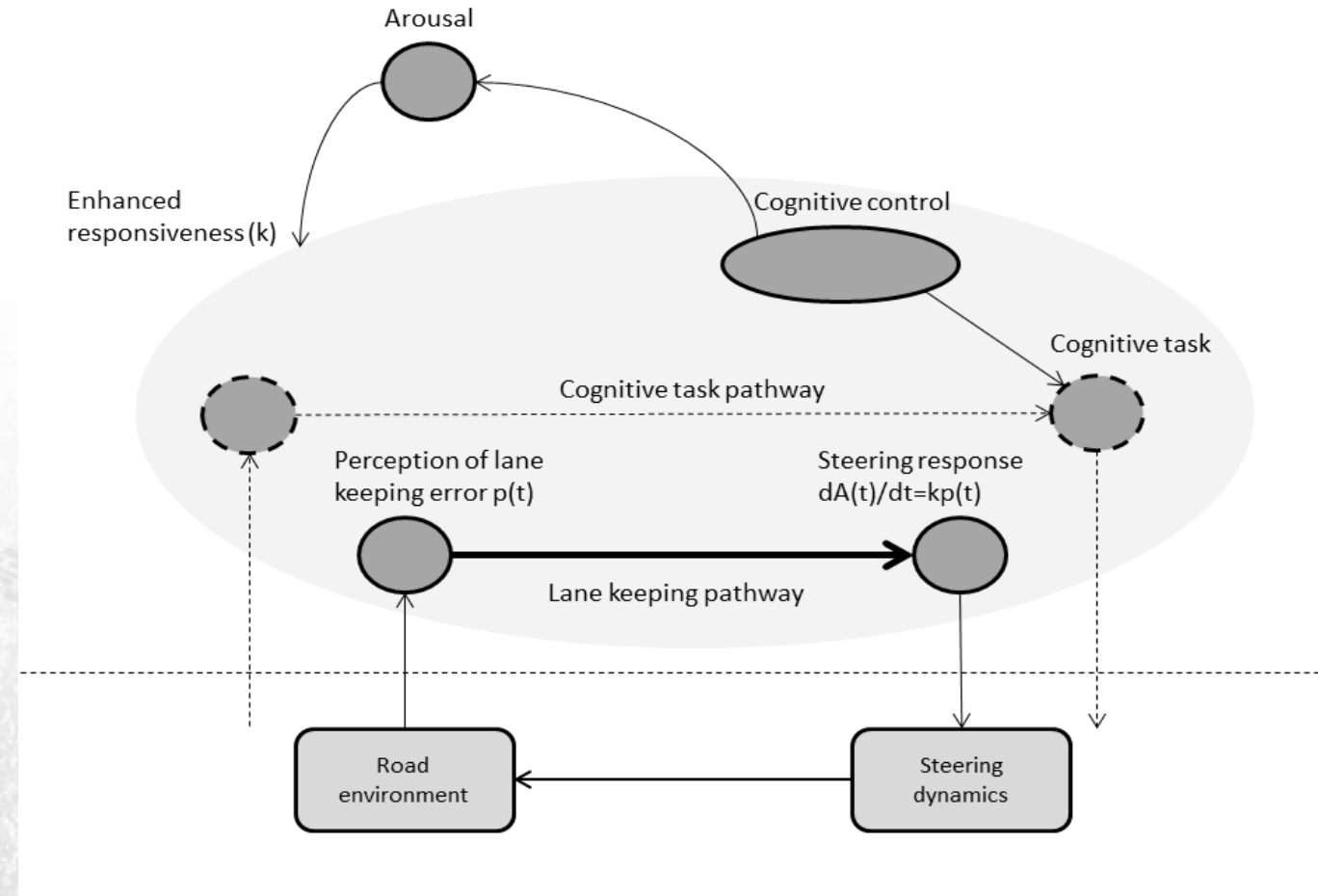
# Novel hypothesis: “The cortical arousal enhancement hypothesis” (Engstrom et al., 2017)

- ❑ Neural responsiveness, modulated by cortical arousal, determines the driver’s sensitivity to lane keeping error
- ❑ Neuroscientific support
  - Global neural enhancement during the deployment of cognitive control related to neuromodulatory processes originating in the reticular activation system in the brainstem (Aston-Jones and Cohen, 2005; Gilzenrat, Nieuwenhuis and Jepma, 2010; Posner and Fan, 2008)
  - Key effect is to increase the *gain* in cortical neurons, thus making them more responsive to stimulus input (Shea-Brown, Gilzenrat and Cohen, 2008; Servan-Schreiber, Prinz and Cohen, 1990)
- ❑ Higher arousal induced by cognitive load -> increases sensitivity
- ❑ Lower arousal induced by drowsiness -> reduces sensitivity
- ❑ Single mechanism may account for both effects



# Conceptual model (based on Engström et al., 2017)

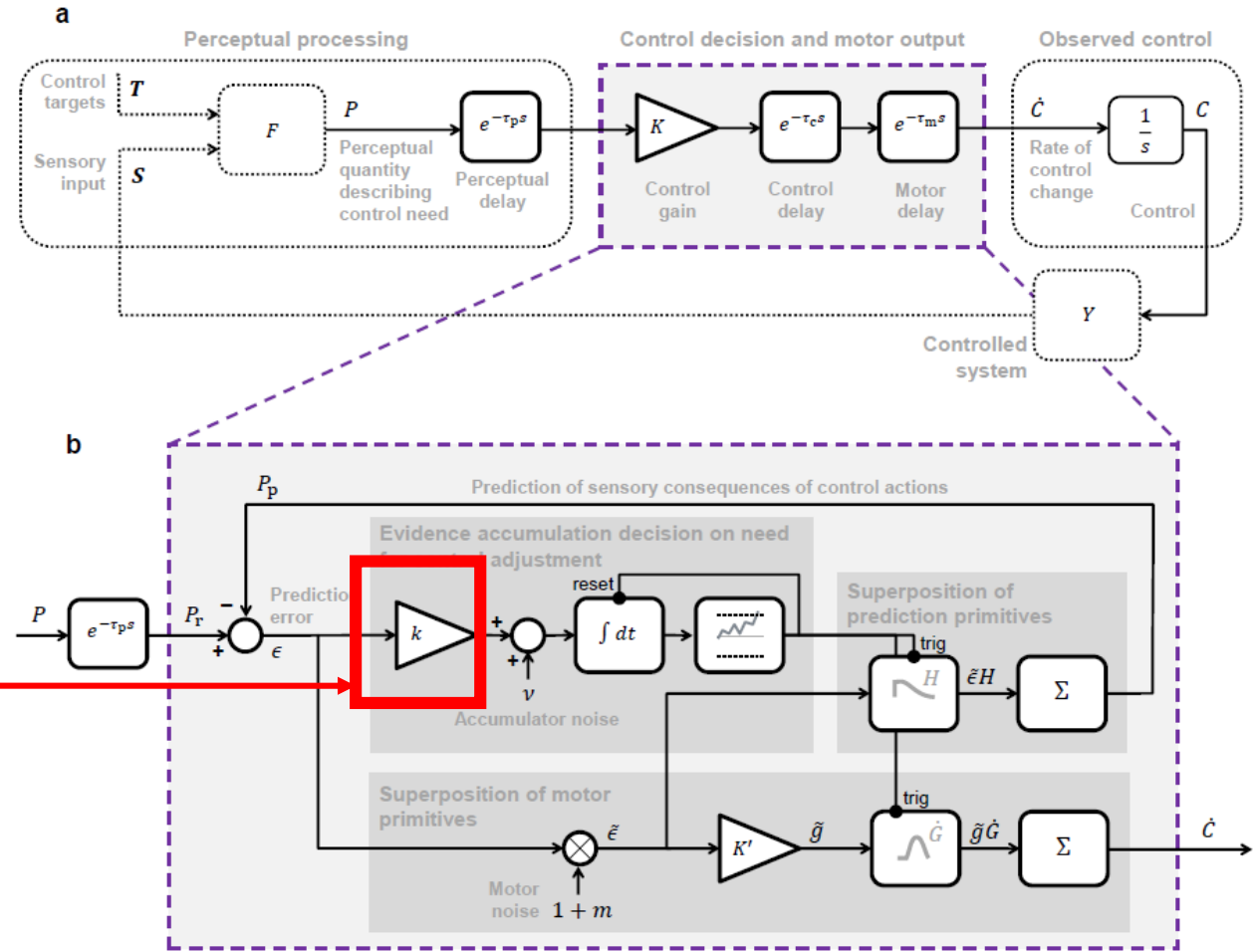
- ❑ Lane keeping is a strongly automatized task, governed by a strong neural pathway
- ❑ Performing cognitively loading secondary task (e.g., phone conversation) increases global cortical arousal
- ❑ Increased arousal enhances the responsiveness of both the cognitive task pathway and the lane keeping pathway
- ❑ Neural responsiveness can be modelled in terms of the rate of neural evidence accumulation (Jepma et al., 2009; Ratcliff and van Dongen, 2011)





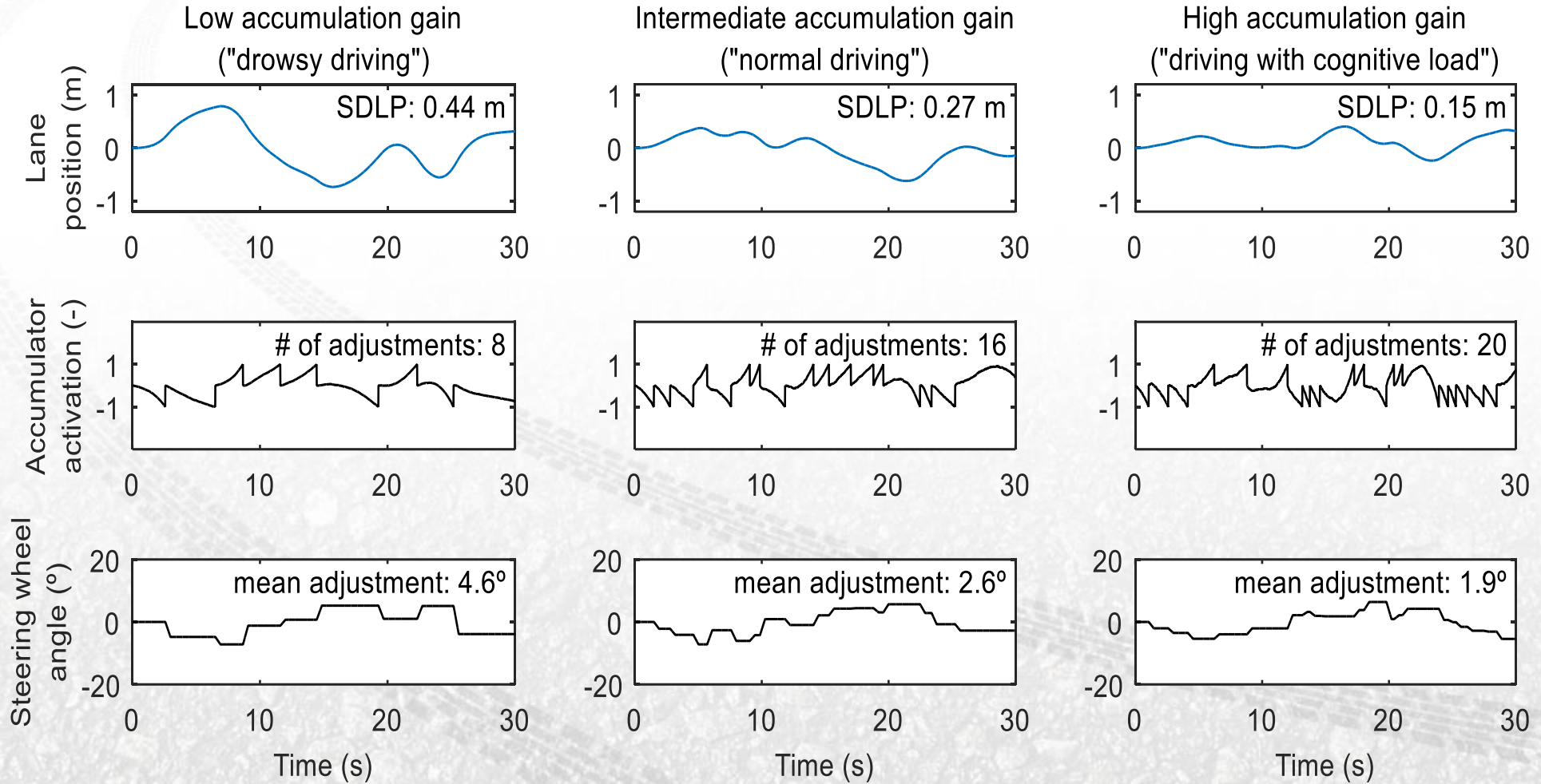
# Computational steering model (Markkula, 2014; Markkula et al., submitted)

- ❑ General framework for sensorimotor control
- ❑ Based on contemporary neuroscientific models of perceptual decision-making (e.g., Gold and Shadlen, 2001)
- ❑ Intermittent control adjustments occur after integration to threshold of perceptual evidence for the need of control (in this case the perceived lane keeping error)
- ❑ Neural responsiveness represented by the **accumulation gain  $k$**
- ❑  $k$  scales up with increases in arousal (due to cognitive load) and down with reduced arousal (due to drowsiness)



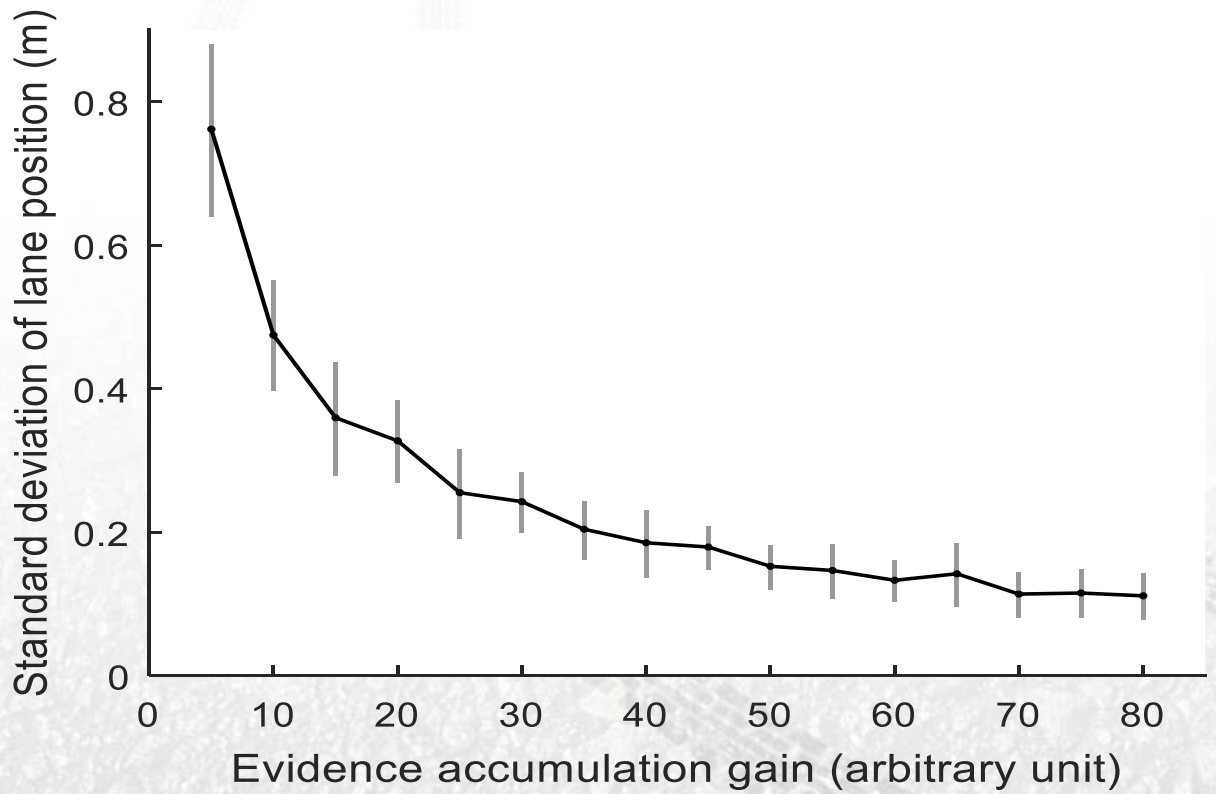
See <https://arxiv.org/abs/1703.03030> for a pre-published version of Markkula et al., (submitted)

# Simulation results (1)

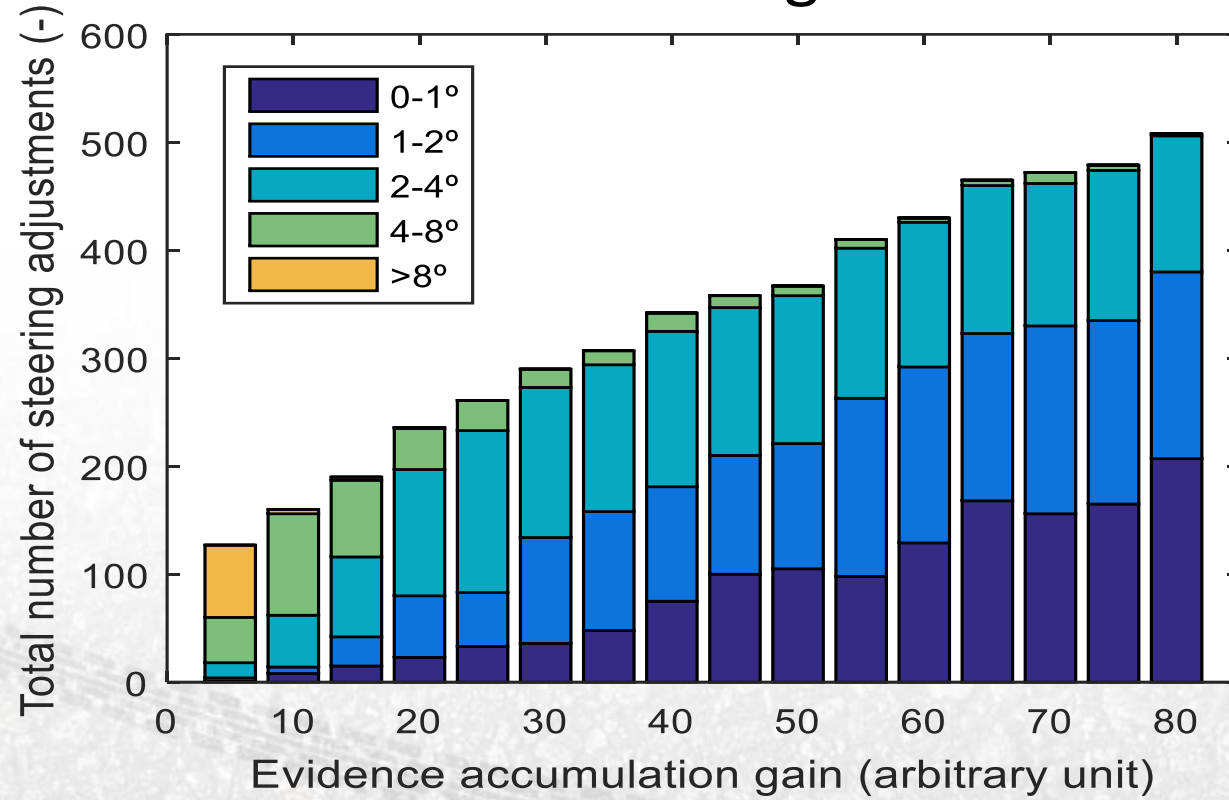


# Simulation results (2)

## Lane keeping



## Steering



“drowsy driving”      “normal driving”      “cognitive load”

“drowsy driving”      “normal driving”      “cognitive load”



# Interpretation

## □ Replicates effects in literature

- Drowsiness: Increased lane keeping variability, fewer small steering corrections but more large corrections
- Cognitive load: Reduced lane-keeping variability, increase in *small* steering corrections

## □ Mechanism, drowsiness

- Reduces the evidence accumulation gain (drowsiness reducing “arousal”)
- Takes longer for a given perceived lane keeping error to generate a steering correction
- Steering action is not triggered until the lane deviation has grown relatively large
- Large steering correction required to bring the vehicle back to the desired heading

## □ Mechanism, cognitive load

- Increasing the evidence accumulation gain (cognitive load increasing “arousal”)
- Steering corrections triggered earlier
- Increased frequency of smaller steering corrections
- Improved lane keeping



# Conclusions

- ❑ The simulation results support to the idea outlined in Engström et al. (2017) that performance effects on lane keeping can be explained in terms of cortical arousal
- ❑ This suggests that drowsiness and cognitive load can be viewed as opposite ends on a single spectrum (with respect to their effects on lane keeping).
- ❑ Representing this spectrum by a single accumulation gain parameter quantitatively reproduces the lane keeping performance and steering effects reported in the literature for both drowsiness and cognitive load.

