

Development and Validation of a Luminance Camera

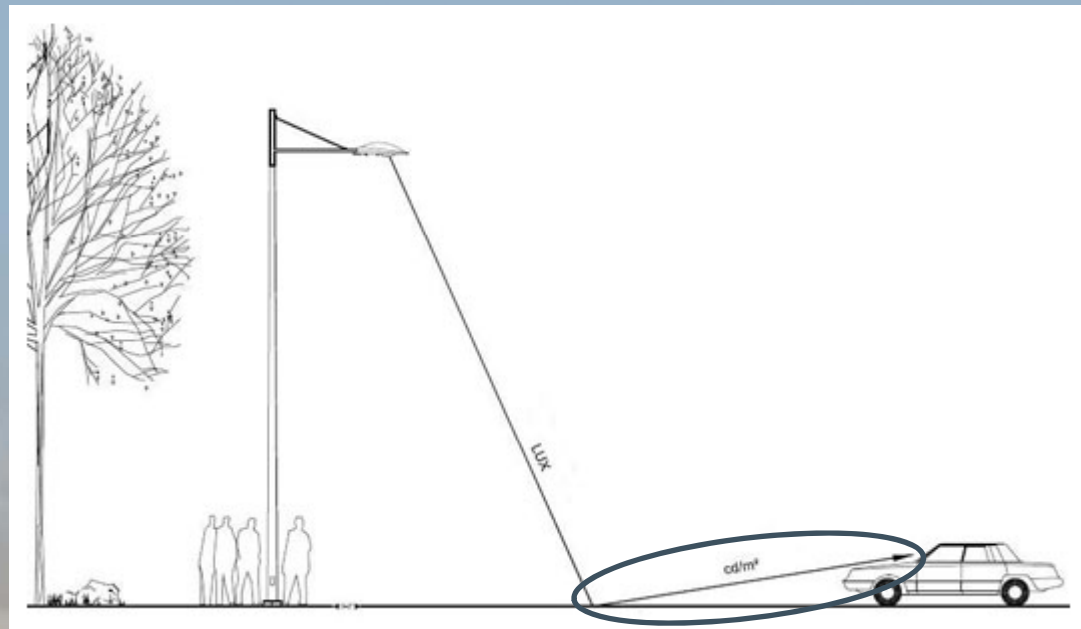
Jason E. Meyer, Ronald B. Gibbons, Christopher J. Edwards
Virginia Tech Transportation Institute

Driving Transportation with Technology



Background

Luminance - amount of visible light leaving a point on a surface in a given direction



From: Schröder

Background

- Static Photometers

- PRO:

- Capture luminance data for entire scene in image
 - Fan to decrease temp. → decrease image noise

- CON:

- Unable to capture dynamic data in rapid succession

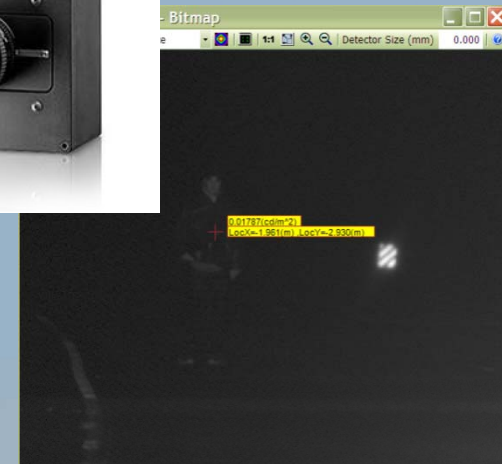
- Hand-held luminance meters

- PRO:

- Capture luminance data for specific points of interest

- CON:

- Time-consuming for multiple points of interest
 - Unable to conduct future analysis since no image is recorded



Goals

1. Calibrate a digital video camera to a photometer
 - Develop rapid method of image capture for calibration
2. Develop working system for dynamic video capture
 - Determine optimal manual camera settings or allow automatic, camera-determined settings
3. Determine the level of repeatability and reproducibility (R&R) of the working system
4. Compare results of the working system in a dynamic environment

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Calibration - Equipment

- Radiant Imaging ProMetric still photometer
- Point Grey Grasshopper FireWire digital cameras (“Luminance Cameras”)
- MATLAB Image Acquisition and Processing Toolboxes
- Incandescent 200-watt light bulb
- High-Pressure Sodium (HPS) 400-watt street luminaire



242 mm

154 mm



29 mm

44 mm



Calibration - Procedure

- Controlled environment
- Simultaneous image capture with ProMetric photometer and Luminance Cameras
 - Software automatically adjusts Luminance Camera variables

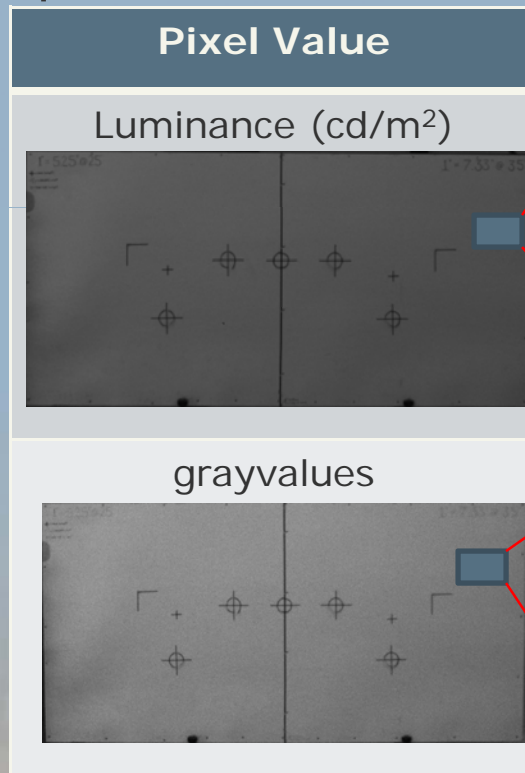


Light Level (cd/m2)	24.1, 15.6, 7.99, 1.87
Camera Gain (dB)	24, 21, 18, 15, 12, 9, 6, 3, 0, -2.25
Camera Shutter (ms)	267, 213, 159, 105, 51, 41, 36, 31, 26, 21, 16, 11, 6, 1

4 Light levels
10 Gain values chosen
x 14 Shutter values chosen
560 images captured by Luminance Camera

Calibration - Procedure

Overlay of images completed automatically through software

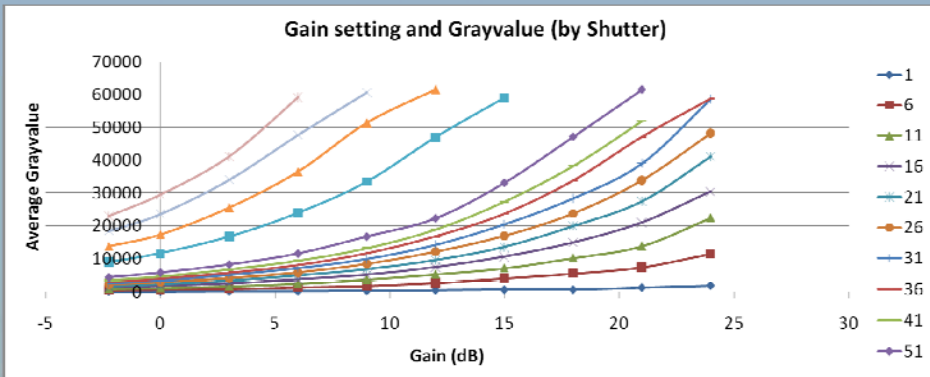


2.13	2.13	2.10
2.13	2.13	2.10
2.08	2.08	2.13

2608	2704	2816
2704	2928	2624
3152	2848	2656

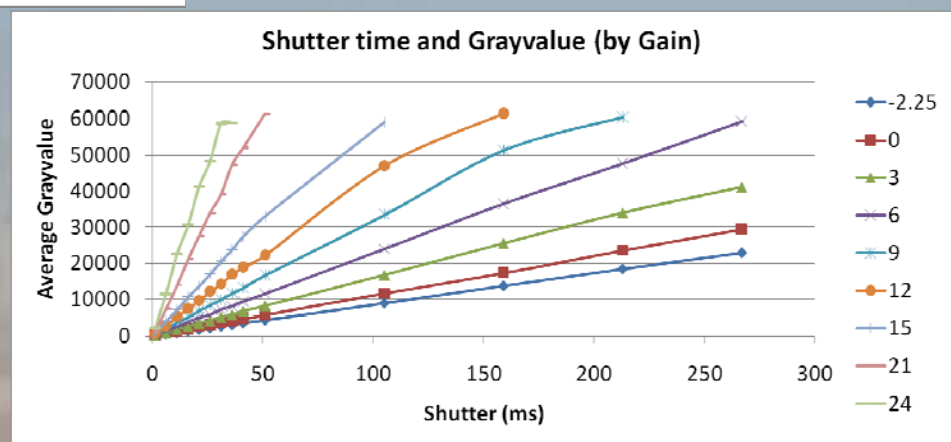
Calibration - Results

Pixel analysis



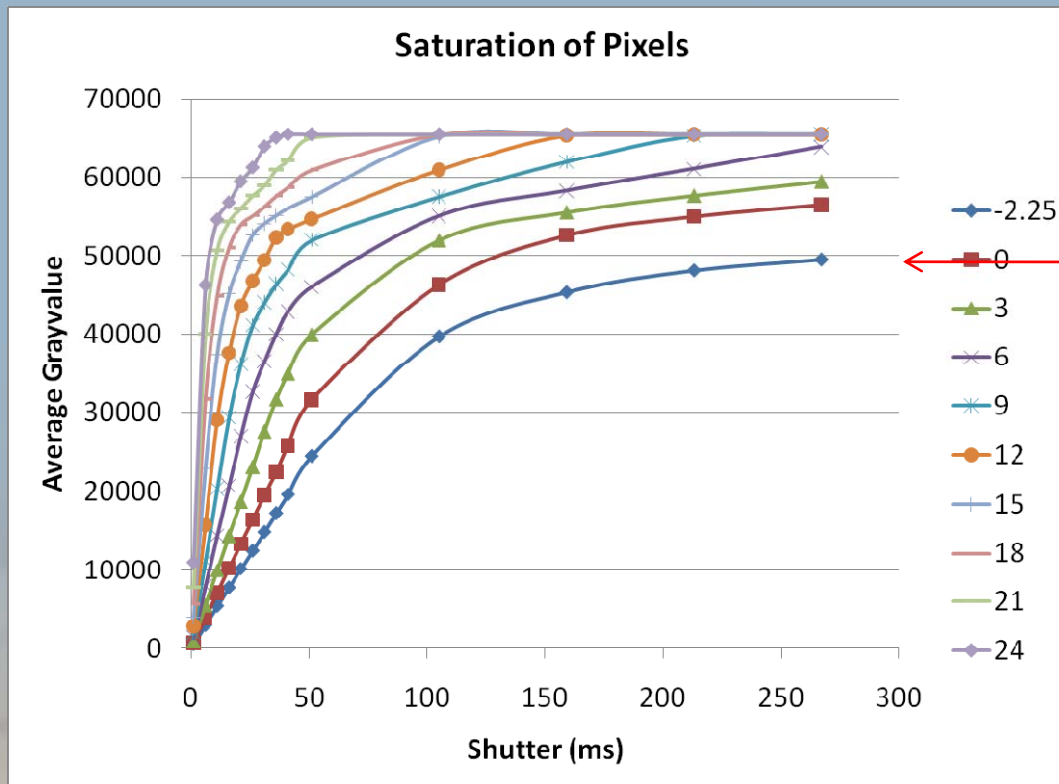
Positive relationship of Luminance Camera grayvalue and gain

Positive relationship of Luminance Camera grayvalue and shutter



Calibration - Results

- Level of pixel saturation (by gain)

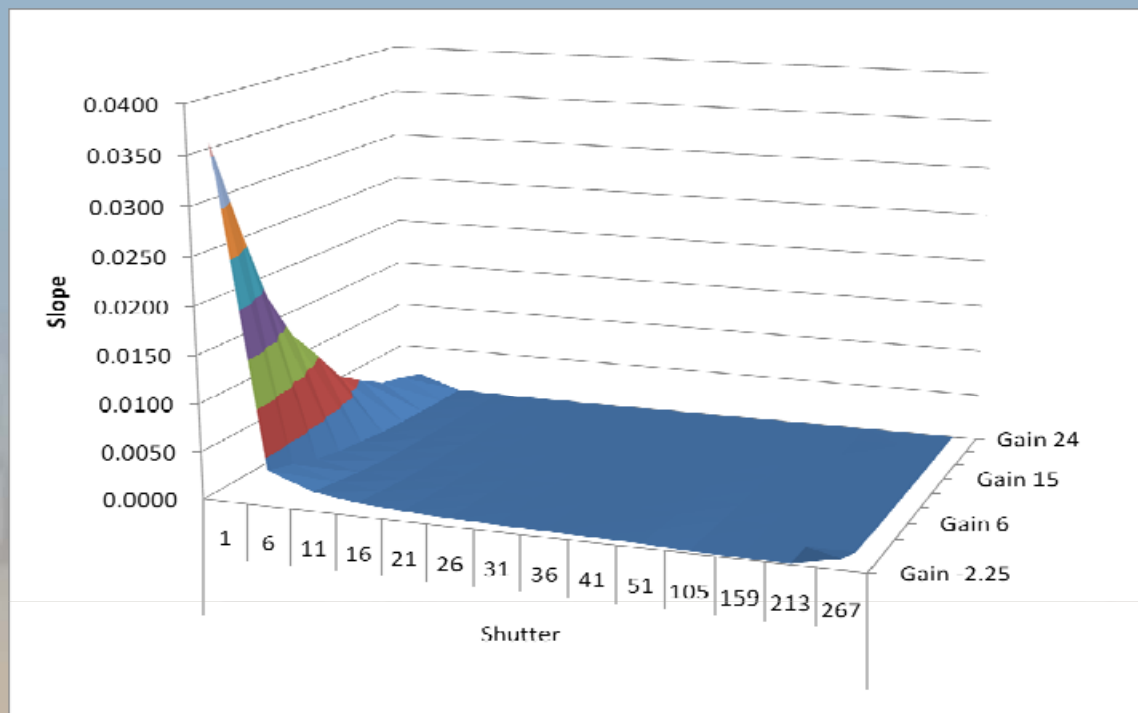


Grayvalues > 50,000
taken out of analysis

Calibration - Results

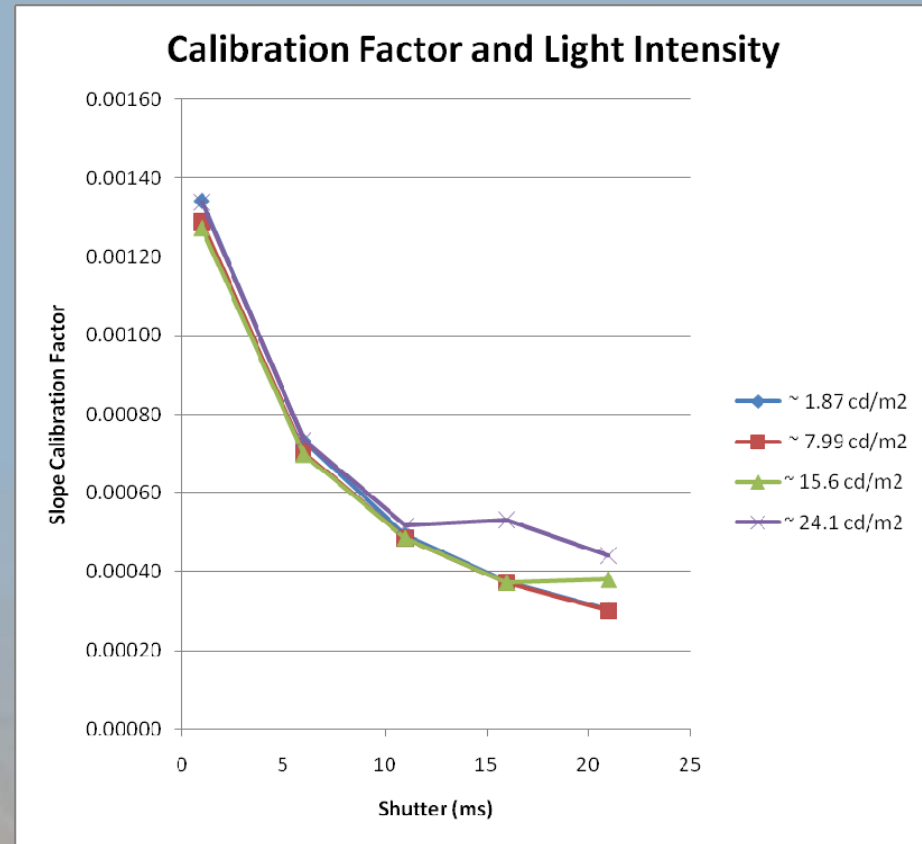
Calibration Slope for each
gain and shutter
combination

$$= \frac{\text{Photometer Luminance}}{\text{Luminance Camera grayvalue}}$$



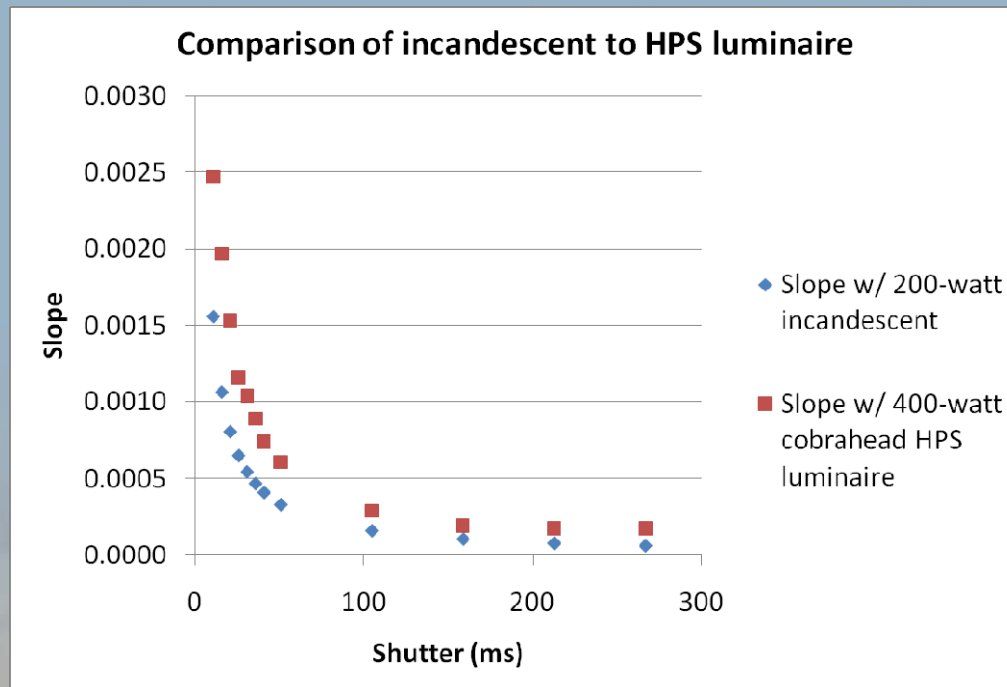
Calibration - Results

Calibration factor
similar across light
intensities



Calibration - Results

Impact of spectral distribution of luminaire



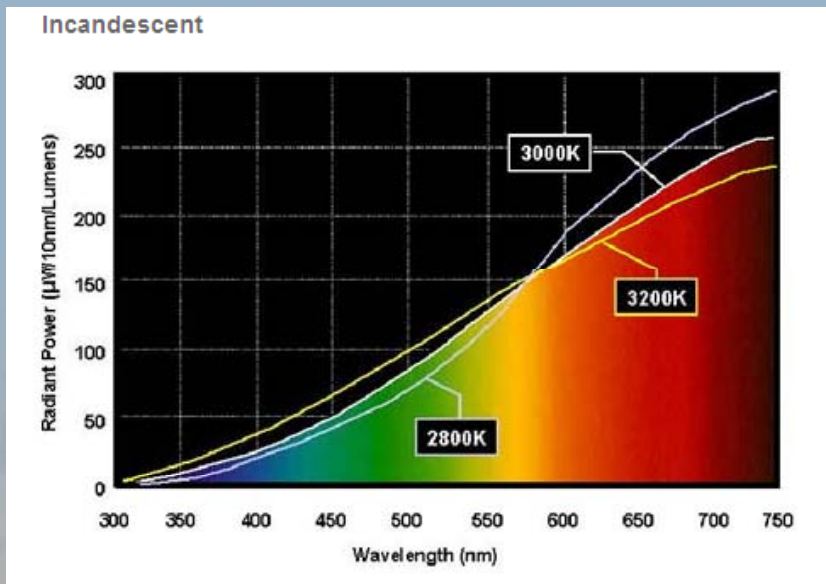
- Different calibration factor needed for different lighting
- Larger value needed for HPS lighting than incandescent lighting

Calibration - Results

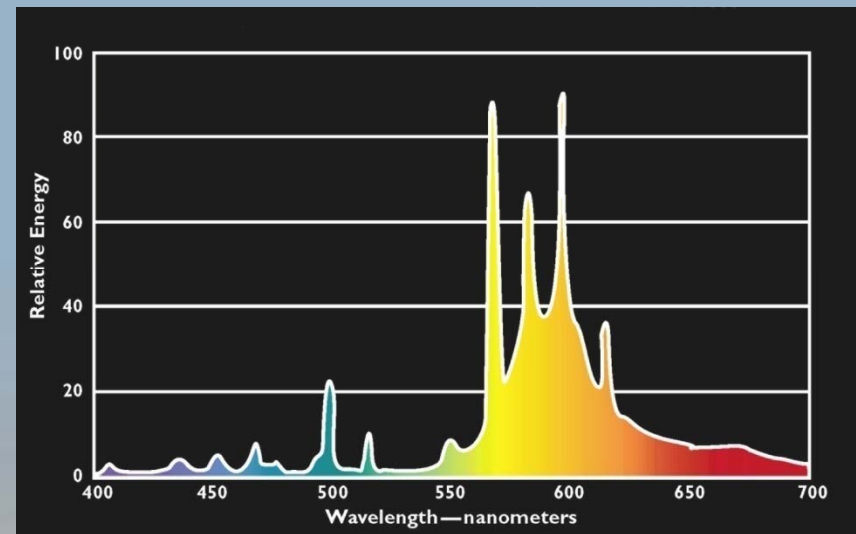
Spectral distributions

Incandescent

High-pressure sodium



From: GE Lighting



From: University of Chicago

Calibration - Discussion

- Multiple cameras calibrated to photometer
- Rapid method developed
 - Automated
 - Image capture
 - Overlay of images
 - Calculation of calibration factors for multiple gain and shutter combinations
- Spectral distribution of light source impact on calibration process

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Dynamic Evaluation - Procedure

- Vehicle equipped with 2 Luminance Cameras manually & auto-configured
- Highway, rural, and downtown areas driven
- Capture images simultaneously at ~4fps
- Select gain and shutter settings for manual camera

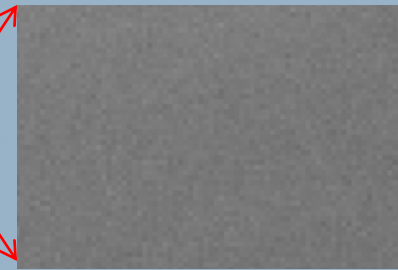


Dynamic Evaluation - Procedure

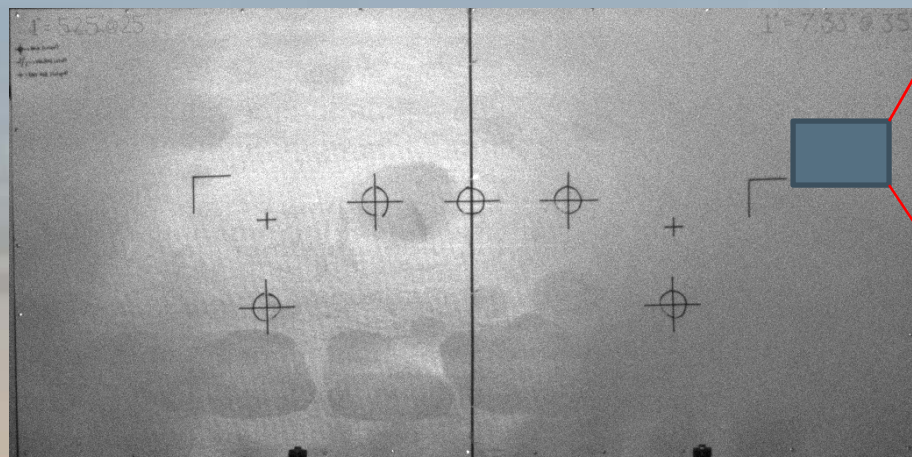
Camera Setting Selection

Impact of gain on image noise level

Gain = 0dB



Gain = 24dB

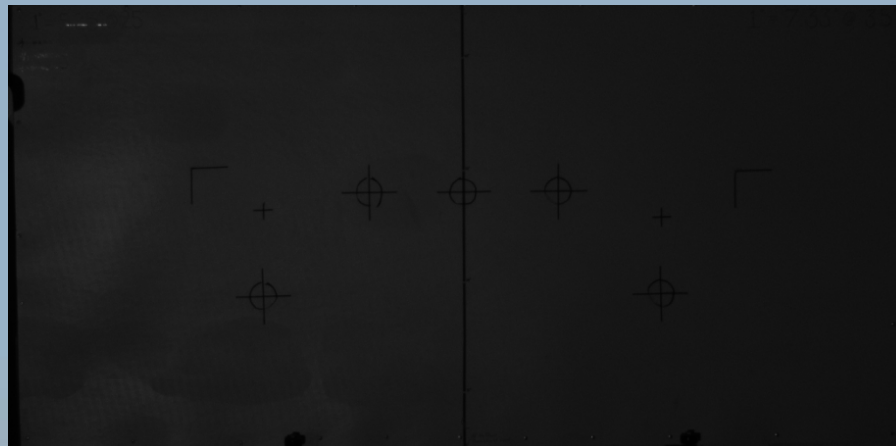


Dynamic Evaluation - Procedure

Camera Setting Selection

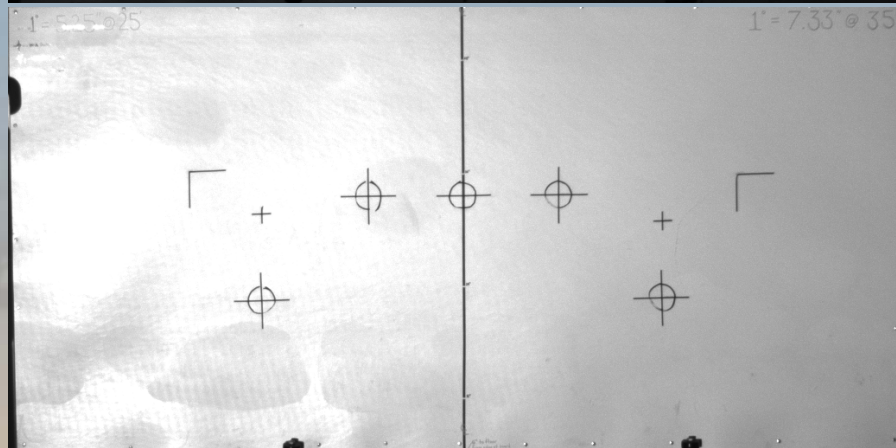
Impact of shutter on image

Shutter = 6ms



- Dark quality
- Difficulty distinguishing targets or objects of interest

Shutter = 51ms



- Reach pixel saturation quickly with glare


Dynamic Evaluation - Procedure

Camera Setting Selection

Estimation of maximum luminance

Darkened
image

High pixel
saturation



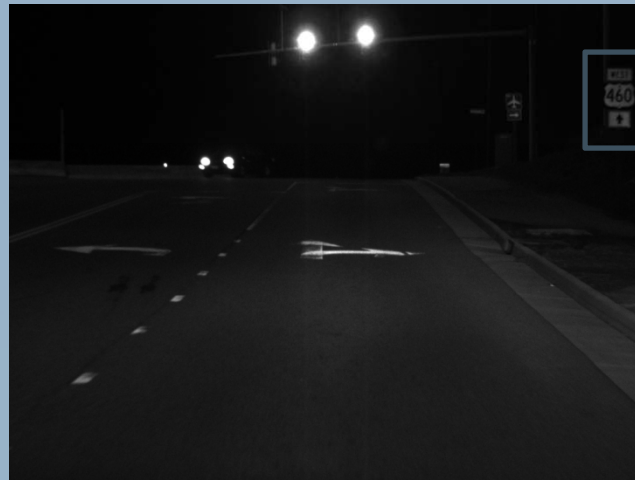
	SHUTTER (ms)														
GAIN (dB)	1	6	11	16	21	26	31	36	41	51	105	159	213	267	
-2.25	899.4	172.6	96.2	66.6	48.4	40.6	34.7	30.1	26.5	21.7	10.8	14.0	6.8	7.3	
0	732.1	120.8	69.1	47.2	39.3	32.2	25.9	23.2	20.7	15.8	7.8	5.4	3.6	3.0	
3	477.8	89.3	49.2	34.9	26.8	21.7	19.3	15.0	14.0	12.5	5.5	3.5	2.7	2.2	
6	332.8	64.0	35.1	24.5	19.4	15.2	13.3	12.6	9.9	7.7	3.7	2.5	1.9	1.6	
9	214.1	40.6	23.4	17.6	12.6	10.0	9.6	7.7	6.1	5.5	2.8	1.7			
12	165.4	33.6	18.6	12.0	9.7	7.5	6.1	5.6	5.2	3.9	2.0				
15	107.3	22.9	12.7	9.8	6.8	5.4	4.4	3.7	3.2	2.7	1.7				
18	81.2	14.8	8.2	6.2	3.9	3.2	2.5	2.4	2.0	1.8					
21	56.1	12.1	6.9	3.8	3.3	2.6	2.2	1.8	1.8						
24	41.8	7.0	5.2	2.4	2.0	1.8	1.8	1.7							

Increase in image noise

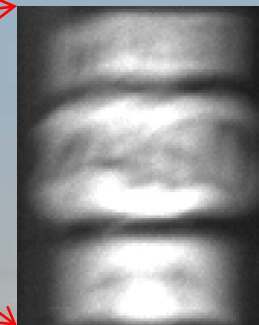
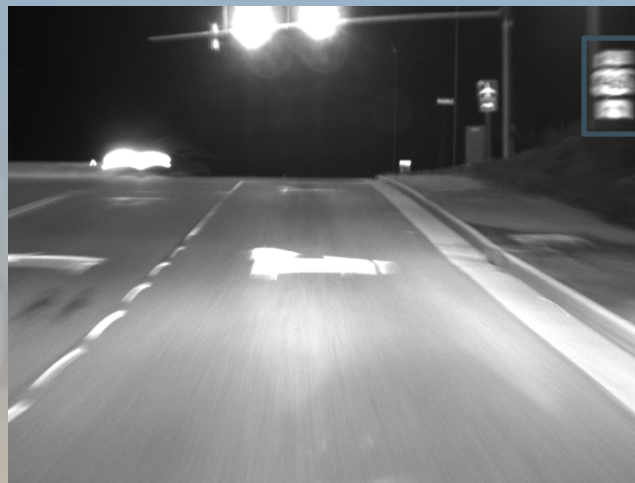


Dynamic Evaluation - Results

Manual



Automatic



High presence of blurring and saturation with auto configuration

Dynamic Evaluation - Discussion

- Auto-enabled
 - Blur
 - Oversaturation
- Manually enabled gain and shutter
 - Appropriate combinations found for multiple road settings
 - Ex. Downtown area → low shutter

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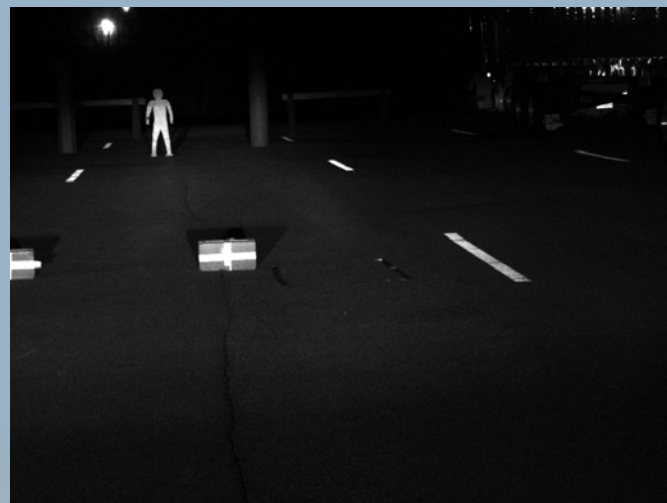
R & R Evaluation

- Repeatability – level of data consistency over time
 - Reproducibility – level of data consistency among different users
1. Perform multiple trials of data collection
 2. Measure variance in data
 3. Where is variance found?
 - In device/camera = repeatability
 - In user of device/camera = reproducibility
 - < 10% → “acceptable” variance
 - 10-30% → “may be acceptable”
 - > 30% → “unacceptable”

Automotive Industry Action Group (AIAG). (2002). *Measurement systems analysis (3rd ed.)*

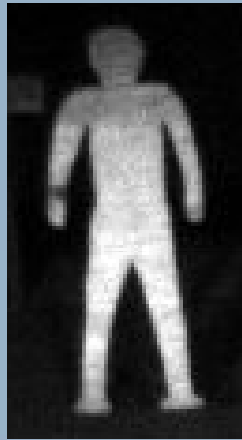
R & R Evaluation - Procedure

- Environment without overhead lighting selected
- Targets/objects of interest displayed for measurements
- Luminance Cameras equipped in vehicle
- Reproducibility
 - 3 drivers/users parking car, illuminating environment
- Repeatability
 - 2 cameras, manually set
 - Multiple images taken
- Calculated mean luminance of selected targets



R & R Evaluation - Results

“Pedestrian”



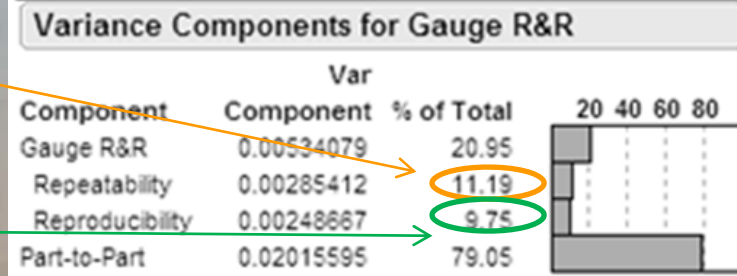
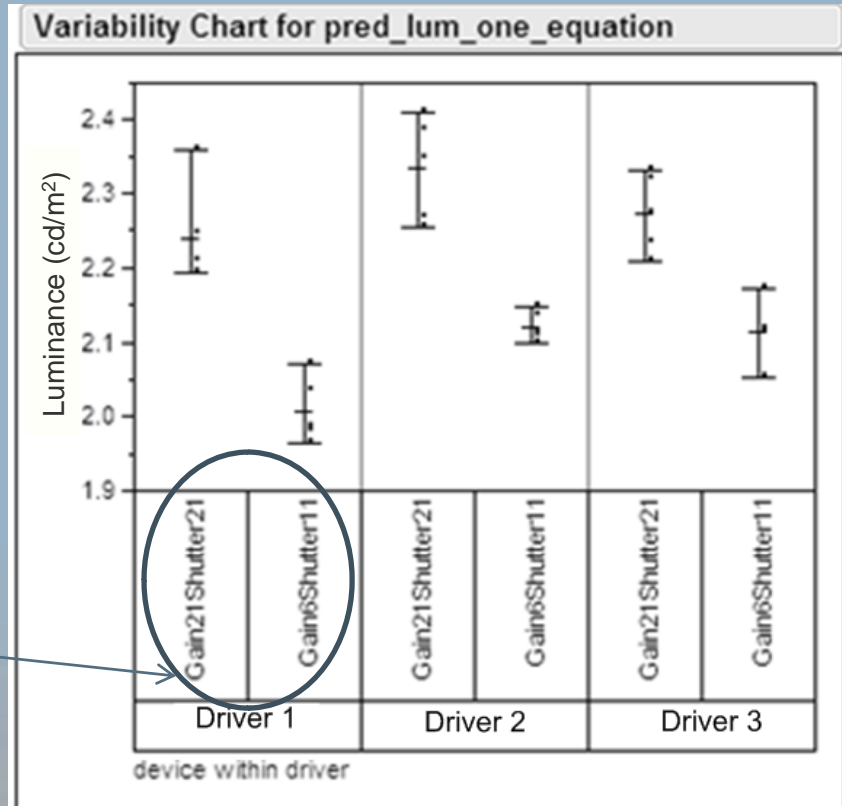
2 cameras, manually set gain and shutter

Camera variance

10-30% “may be acceptable”

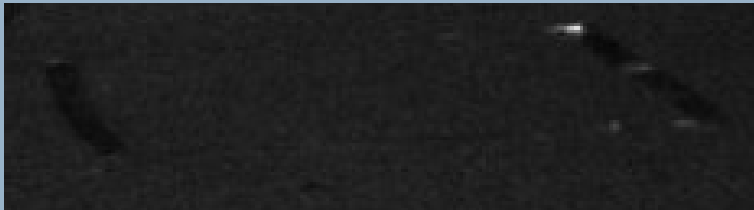
Variance among users

< 10% “acceptable”



R & R Evaluation - Results

Selected area of pavement

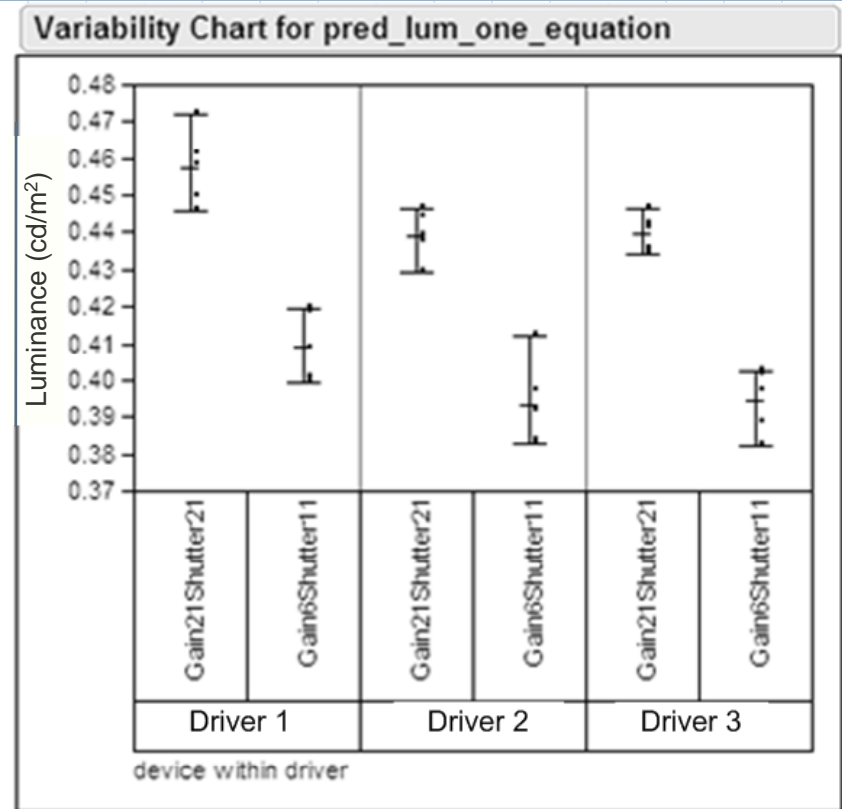


Camera variance

< 10% “acceptable”

Variance among users

< 10% “acceptable”



Variance Components for Gauge R&R

Component	Var	Component	% of Total
Gauge R&R	0.00015907		12.86
Repeatability	0.00007468		6.04
Reproducibility	0.00008438		6.82
Part-to-Part	0.00107752		87.14

R & R Evaluation - Discussion

- Luminance Camera performance
 - Reliable across time
 - Reproducible among users
- Considerations to prevent oversaturation
 - Targets/objects of interest
 - Camera settings

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Dynamic Roadway Comparison - Procedure

- Vehicle equipped with photometer & Luminance Camera
- Drive public roads
 - Luminance Camera - Continually capture video
 - Photometer - Stop vehicle, capture image of scene
- Corresponding images later matched
 - Targets/objects of interest selected (pavement markings)
 - Mean luminance of targets calculated

Dynamic Roadway Comparison - Results

Photometer image



Mean value = 2.508 cd/m²

Luminance Camera image (Gain = 0dB, Shutter = 26ms) →



Mean grayvalue = $\frac{2331.0}{\times 0.0011}$
2.5641 cd/m²

Calibration factors

- HPS = 0.0011
- Incandescent = 0.00065

$\frac{2331.0}{\times 0.00065}$
1.5152 cd/m²

Dynamic Roadway Comparison - Discussion

- Successful comparison of photometer to Luminance Camera
- Spectral distribution issues are evident

Conclusions

- Rapid method of camera calibration developed
- Cameras calibrated to multiple settings (to allow for different environments)
- Repeatability and Reproducibility of the camera system evaluated
- System evaluated in dynamic environment

Future Steps/Limitations

- Calibration improvements
 - Diffuse calibration surface
 - Photopic filter
 - Decrease spectral impact
 - Better indication of what human eye sees
- Dual camera approach in order to capture wide range of luminance in environment
- Methods to reduce camera temperature/decrease image noise