

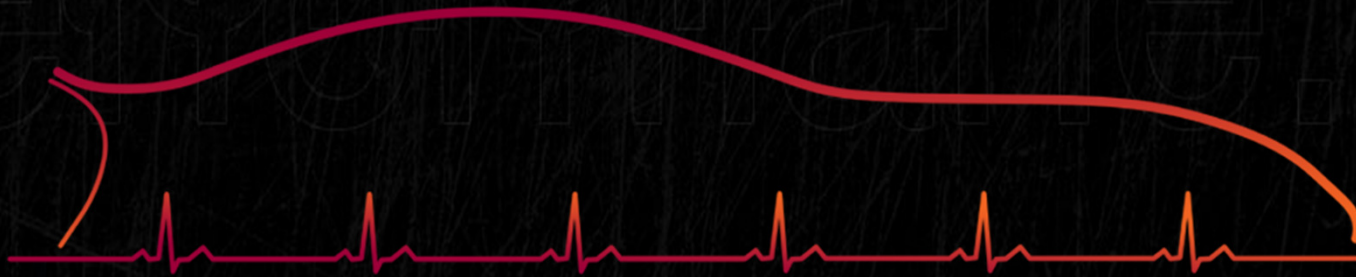
**V**EHICLE **T**ERRAIN **P**ERFORMANCE **L**ABORATORY

# Large High-Resolution Display for Terrain Visualization

RPUG 2010



Haeyong Chung  
Computer Science  
Vehicle Terrain Performance Lab



**V**EHICLE **T**ERRAIN **P**ERFORMANCE **L**ABORATORY

# Large High-Resolution Display for Terrain Visualization

RPUG 2010



John B. Ferris  
Associate Professor of Mechanical Engineering  
Director, VTPL  
Virginia Tech

# Outline

Background on VTPL

Motivation for LHRD

# Scope

## Vehicles

- Passenger cars and trucks
- Commercial off-road and military vehicles
- Motorcycles
- Race cars
- Chassis components
  - Tires
  - Springs, dampers, bushings,...



# Scope

## Terrain

- Highway and public roads
- Race tracks
- Off-road
- Proving Ground

## Performance

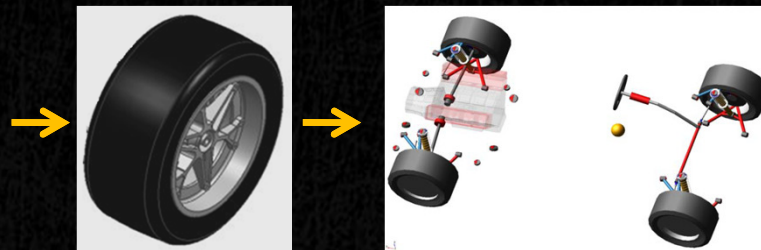
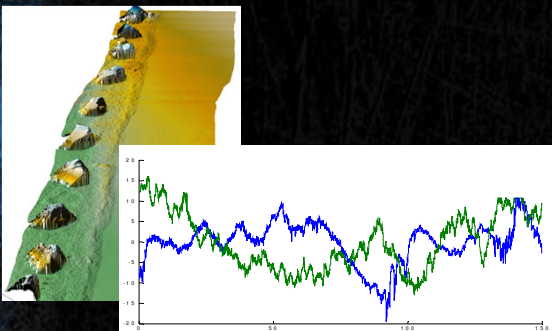
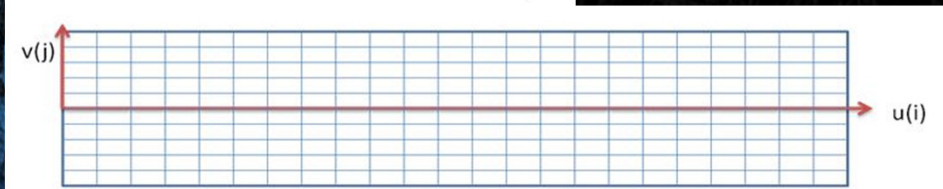
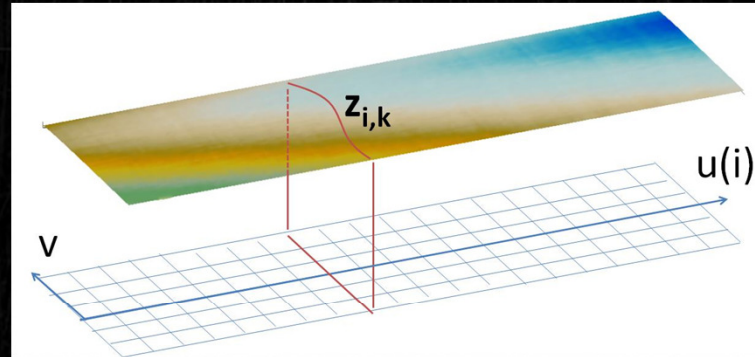
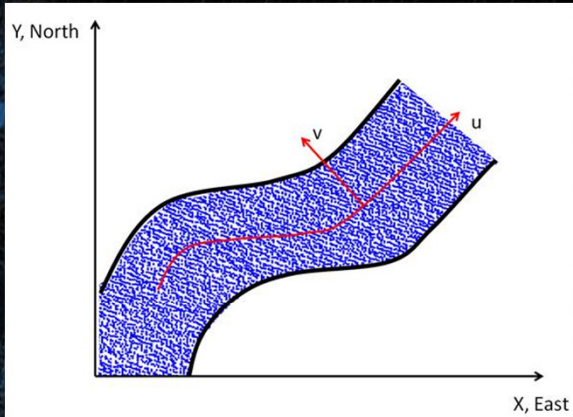
- Ride
- Handling
- Mobility
- Durability
- Reliability



# Terrain Measurement



# Terrain Modeling



John Ferris  
www.me.vt.edu/VTPL



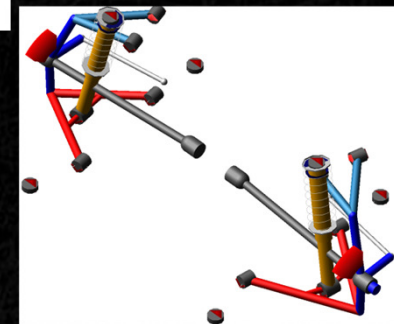
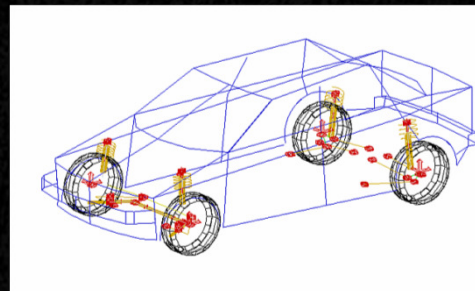
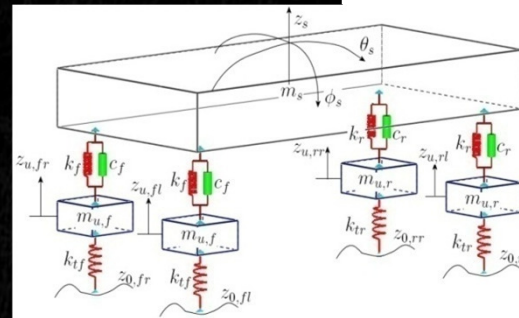
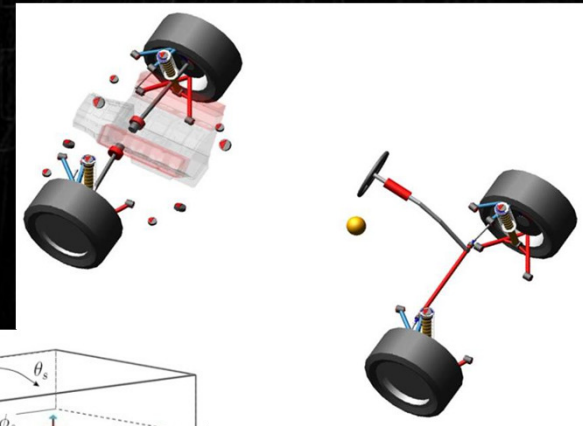
# Vehicle Modeling

## Multi-Body Dynamics

- ADAMS
- CarSim
- MATLAB/Simulink

## Finite Element Analysis

- MSC/Nastran
- Abaqus / Simulia
- Ansys





# Performance Prediction

## Objective

Make informed decisions early in design process

## Applications

- Ride and handling metrics
- Durability test schedules
- Reliability-Based Design



# Motivation

- The pavement distortions should be inspected properly to monitor the health, safety and potential ride quality of roads.
- The inspectors mainly depend on visual inspection and visually decide which pavement should be repaired



# Problems

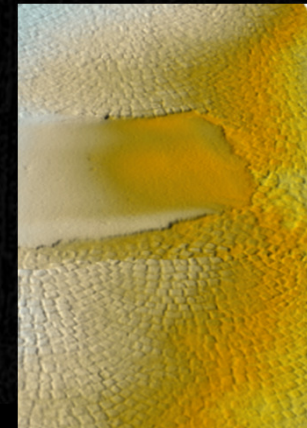
- Physical, *in situ* inspection is costly, requires that the road be closed to traffic
- Dangers to the inspector posed
- Post measurement inspection is less costly but is still based on 2D
- Automated methods for computer detection and analysis of cracks required for conducting validation and verification testing

# Goals

- New method for pavement surface condition inspection that combines
  - Ability of physically inspection of in situ inspection
  - Speed, safety and a wider field of view and very high resolution offered by post-measurement inspection
- Fusing video data with high-fidelity terrain topology measurements
- Visualizing them on LHRD
- Provide quantitative data to eliminate or supplement components of current visual inspection procedures

# VTMS Data

- A single dataset includes several millions of points.
- Difficult to visualize multiple VTMS datasets in small displays and desktop systems
- Massive amounts of computing power are required to render the high-fidelity VTMS data
- The resolution of the VTMS datasets is easily beyond the capability of current computer display and graphics systems



## Large High-Resolution Display (LHRD)

- Much higher DPI (Dots Per Inch) than general displays
- Wider field of view to terrain data
- Terrain visualization on a scale comparable to real life



## Expected Benefits of the New Platform

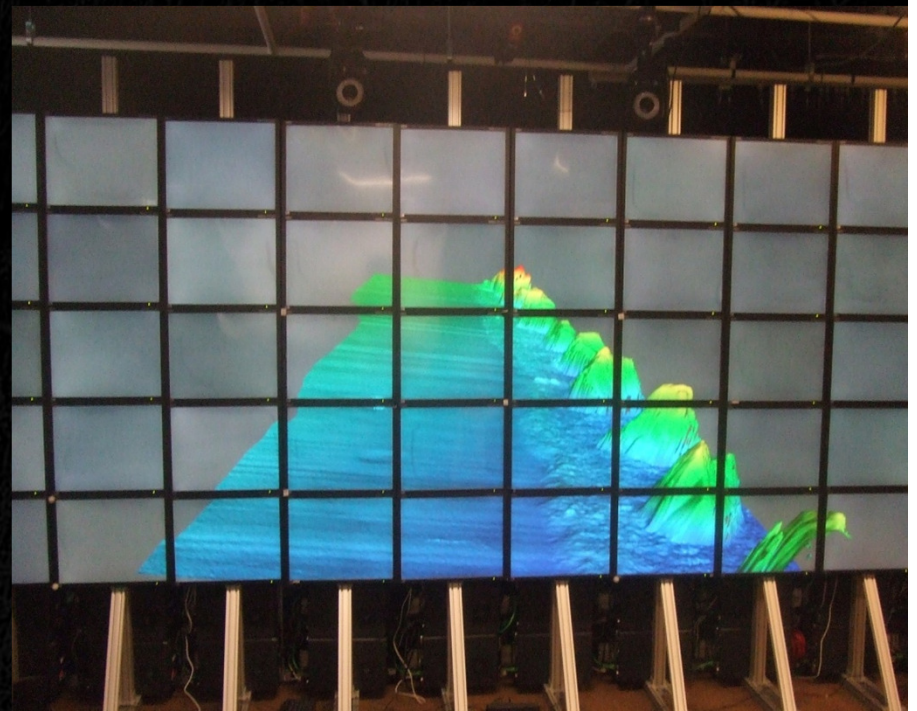
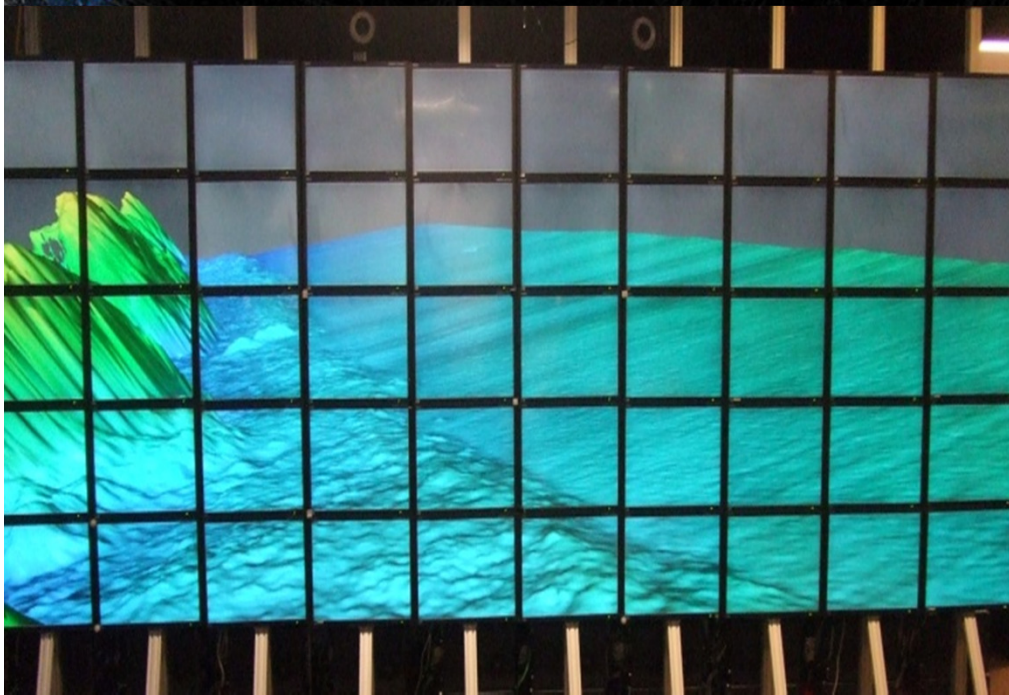
- A new method for 3D pavement condition inspection
- A new platform by which automated crack inspection and analysis software can be verified and validated
- An understanding of the run-to-run variation in roughness estimates
- Quality control and assurance procedures for pavement condition data collection

# Visualization Prototypes 1





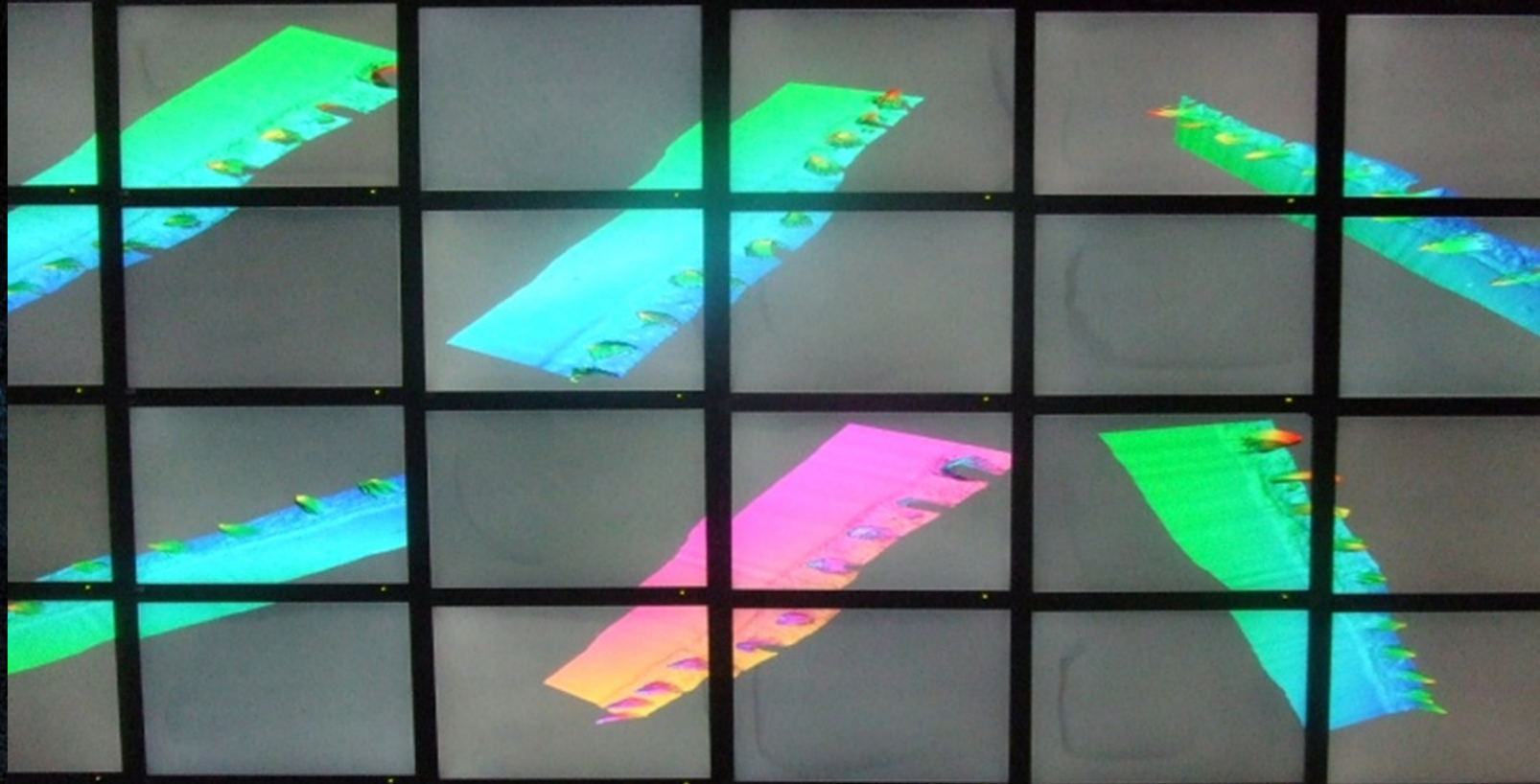
# Visualization Prototypes 2



# Visualization Prototypes 3



# Visualization Prototypes 4



# Summary

- Developing a new method for pavement surface inspection
- VTMS data and LHRD provides a novel platform to inspect pavement interactively
- Understanding of the run-to-run variation in roughness estimates
- Support quality control and assurance procedures for pavement condition data collection.